# CASA Polarization Capabilities & Plans

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#### **Status**

- Essential linear feed basis on-axis instrumental polarization calibration treatment supported and working
  - Calibrator  $Q_{*}\mathcal{U}$  estimation (from gains and from cross-hands)
  - Cross-hand phase spectrum estimation
  - Frequency-dependent Instrumental polarization solution (linearized, but including source polarization terms)
  - General matrix instrumental polarization correction
- Observational requirements (expectations):
  - Strongly (> few %) linearly polarized calibrator
  - Parallactic angle coverage sufficient for  $Q\mathcal{U}$  estimation (and therefore also for other polarization-specific steps)
- Simplified and degenerate approaches (e.g., unpolarized D calibrator, if available) also supported (position angle calibration for linears TBD)
- Pipeline support TBD

# Status (cont)

- EVLA support
  - <1 GHz (linear feed basis): ALMA treatment applicable (polarized calibrators: pulsars)
  - ->1 GHz (circular feed basis): traditional instrumental polarization treatment, with options for generalization (e.g., general D matrix correction)
    - Wider bandwidth==worse instr. pol.; dynamic range consequences
  - Ionospheric model corrections added in v4.3 (J. Kooi, Ulowa)
    - A non-trivial example of 'forward' gain-like calibration

# In the beginning (~2011)...

- Conditions:
  - Only polarized calibrators
  - No online XY-phase instrumentation
- ➤ Use strong and strongly polarized calibrators & sufficient parallactic angle coverage to solve for everything
  - Also, a polarized calibrator provides better constraints on an 'absolute' D solution for linear feeds
    - Full matrix correction, including parallel-hands (Stokes 1 dynamic range?)
  - How do the constraints actually work?
- For better or worse, this became the initial 'standard' observing mode (awkward in ALMA ops model which favors shorter observations)

### CASA/ALMA Polarization Calibration Model

Calibration Model:

$$V^{obs} = K^{crs} B^r G^r D^r X^r P V^{mod}$$

- Basic Solve sequence:
  - Normal bandpass ( $B^r$ ) and gain ( $G^r$ ) (parallel-hands):

$$V^{obs} = \underline{B^r} V^{\mathcal{I}}$$
  
 $(B^{r-1} V^{obs}) = \underline{G^r} V^{\mathcal{I}}$  (+estimate  $QU$ )

- Cross-hand delay ( $K^{crs}$ ), phase ( $X^r$ ), and  $Q_rU$  (cross-hands):

$$V^{obs} = \underline{K^{crs}} (B G P V^{IU'})$$

$$(G^{r-1} B^{r-1} K^{crs-1} V^{obs}) = \underline{X^r} P V^{\underline{QUV}} \text{ (+resolve amb)}$$

- Revise  $G^r$ , using IQU (parallel-hands):

$$(B^{r-1} K^{crs-1} V^{obs}) = \underline{G^r} (P V^{IQU})$$

— Instrumental poin ( $D^r$ ), using all of the above (cross-hands):

$$(G^{r-1} B^{r-1} K^{crs-1} V^{obs}) = D^r (X^r P V^{IQU})$$

- (Iteration?)
- Correction:

$$V^{corr} = (P^{-1} X^{r-1} D^{r-1} G^{r-1} B^{r-1} K^{crs-1} V^{obs})$$

### Ideal Visibilities: V<sup>true</sup>

$$V_{XX} = I + Q$$

$$V_{XY} = U + iV$$

$$V_{YX} = U - iV$$

$$V_{YY} = I - Q$$

## Parallactic Angle: P V<sup>true</sup>

$$\begin{split} V_{XX} &= \mathcal{I} + (Q\cos 2\psi + \mathcal{U}\sin 2\psi) &= \mathcal{I} + Q_{\psi} \\ V_{XY} &= (-Q\sin 2\psi + \mathcal{U}\cos 2\psi) + i\mathcal{V} &= \mathcal{U}_{\psi} + i\mathcal{V} \\ V_{YX} &= (-Q\sin 2\psi + \mathcal{U}\cos 2\psi) - i\mathcal{V} &= \mathcal{U}_{\psi} - i\mathcal{V} \\ V_{YY} &= \mathcal{I} - (Q\cos 2\psi + \mathcal{U}\sin 2\psi) &= \mathcal{I} - Q_{\psi} \end{split}$$

### **D** in the Linear Basis - I

#### $V = D P V^{true}$ :

$$V_{XX} = (\mathcal{I} + Q_{\psi}) + (\mathcal{U}_{\psi} + i\mathcal{V})d_{Xj}^{*} + d_{Xi}(\mathcal{U}_{\psi} - i\mathcal{V}) + d_{Xi}(\mathcal{I} - Q_{\psi})d_{Xj}^{*}$$

$$V_{XY} = (\mathcal{I} + Q_{\psi})d_{Yj}^{*} + (\mathcal{U}_{\psi} + i\mathcal{V}) + d_{Xi}(\mathcal{U}_{\psi} - i\mathcal{V})d_{Yj}^{*} + d_{Xi}(\mathcal{I} - Q_{\psi})$$

$$V_{YX} = d_{Yi}(\mathcal{I} + Q_{\psi}) + d_{Yi}(\mathcal{U}_{\psi} + i\mathcal{V})d_{Xj}^{*} + (\mathcal{U}_{\psi} - i\mathcal{V}) + (\mathcal{I} - Q_{\psi})d_{Xj}^{*}$$

$$V_{YY} = d_{Yi}(\mathcal{I} + Q_{\psi})d_{Yj}^{*} + d_{Yi}(\mathcal{U}_{\psi} + i\mathcal{V}) + (\mathcal{U}_{\psi} - i\mathcal{V})d_{Yj}^{*} + (\mathcal{I} - Q_{\psi})$$

- Nice symmetries:
  - d multiplies pure cross-/parallel-hands in the parallel-/crosshands
  - d<sup>2</sup> multiplies other pure parallel-/cross-hand (c.f. antenna-based description)

### **D** in the Linear Basis - II

• Linearized, sorted:

$$V_{XX} = (\mathcal{I} + Q_{\psi}) + (\mathcal{U}_{\psi} + i\mathcal{V})d_{Xj}^{*} + d_{Xi}(\mathcal{U}_{\psi} - i\mathcal{V})$$

$$V_{XY} = (\mathcal{U}_{\psi} + i\mathcal{V}) + (\mathcal{I} + Q_{\psi})d_{Yj}^{*} + d_{Xi}(\mathcal{I} - Q_{\psi})$$

$$V_{YX} = (\mathcal{U}_{\psi} - i\mathcal{V}) + d_{Yi}(\mathcal{I} + Q_{\psi}) + (\mathcal{I} - Q_{\psi})d_{Xj}^{*}$$

$$V_{YY} = (\mathcal{I} - Q_{\psi}) + d_{Yi}(\mathcal{U}_{\psi} + i\mathcal{V}) + (\mathcal{U}_{\psi} - i\mathcal{V})d_{Yj}^{*}$$

### **D** in the Linear Basis -III

• Linearized, sorted,  $dV \sim 0$ , regrouped Stokes

$$\begin{split} V_{XX} &= (\mathcal{I} + Q_{\psi}) + \mathcal{U}_{\psi}(d_{Xj}^{*} + d_{Xi}) \\ V_{XY} &= (\mathcal{U}_{\psi} + i\mathcal{V}) + \mathcal{I}(d_{Yj}^{*} + d_{Xi}) + Q_{\psi}(d_{Yj}^{*} - d_{Xi}) \\ V_{YX} &= (\mathcal{U}_{\psi} - i\mathcal{V}) + \mathcal{I}(d_{Yi} + d_{Xj}^{*}) + Q_{\psi}(d_{Yi}^{*} - d_{Xj}^{*}) \\ V_{YY} &= (\mathcal{I} - Q_{\psi}) + \mathcal{U}_{\psi}(d_{Yi}^{*} + d_{Yj}^{*}) \end{split}$$

- Properties:
  - Constant (per baseline) complex offset proportional to  ${\mathcal I}$  in crosshands
  - d-scaled time-dependent source linear polarization in all correlations

## Specific methods, modes

- (almapolhelpers.py)
- QU from naïve gain(t) ratio:
  - qufromgain
- XY-phase and Q, U:
  - gaincal(gaintype='XYf+QU')
- XY-phase ambiguity resolution:
  - xyamb
- Frequency-dependent D solution ( $Q_{\psi}d$ -sensitive):
  - polcal(poltype='Dflls')
- Sky frame D:
  - dxy
- General matrix correction:
  - Dgen

# Gain calibration absorbs Q, U

 Linear basis: If calibrator has non-zero (and unknown) linear polarization, polarization-dependent gain-like solves will absorb it, e.g.:

$$g_{\chi}' = g_{\chi}(1 + Q_{\psi}/2)^{0.5}$$
  $g_{\gamma}' = g_{\gamma}(1 - Q_{\psi}/2)^{0.5}$ 

- Parallel hands will be 'corrected' for calibrator polarization!
- Cross-hand correction error is 2<sup>nd</sup> order in  $Q_{\psi}$ :  $(1-Q_{\psi}^{2}/\mathcal{I}^{2})^{0.5}$ 
  - Distortion is small (we will rely on this later)
- Formally, desirable to measure  $g_{\chi}$ ,  $g_{\gamma}$  on an unpolarized source, depend on  $|g_{\chi}/g_{\gamma}|$  stability, and use (unpol) T(t)
- QU may be estimated if sufficient  $\psi$  sampling available, and true gain ratio is stable (qufromgain):

$$g_{X}'/g_{Y}' = (g_{X}/g_{Y}) (1 + Q_{Y}/\mathcal{I})^{0.5}/(1 - Q_{Y}/\mathcal{I})^{0.5}$$

$$\approx (g_{X}/g_{Y}) (1 - 2Q_{Y}/\mathcal{I})^{0.5}$$

# Cross-hand phase spectrum

- An artifact of gain calibration reference antenna (refant)
- We do not measure absolute G and B
- Instead, we measure G<sup>r</sup> and B<sup>r</sup>, wherein a reference antenna's phase is fixed to zero in both polarizations, yielding relative phases for all other antennas
  - Differences among antennas in each polarization (separately) are preserved: no effect on parallel-hand calibration
- The refant's cross-hand bandpass phase remains undetected:

$$BG = B^rG^rX^r$$

And uncorrected:

$$\mathbf{G}^{r-1} {}^{r}\mathbf{B}^{r-1} \mathbf{B} \mathbf{G} = \mathbf{X}^{r}$$

$$\mathbf{X}^{r} = \begin{pmatrix} e^{i\rho} & 0 \\ 0 & 1 \end{pmatrix}$$

- X<sup>r</sup> is as interesting as any bandpass phase spectrum in the system
  - (We are subject to its stability)

### Revised factorization

We therefore rewrite the calibration operator equation:

$$V^{obs} = B G D P V^{mod}$$
$$= B^r G^r X^r D P V^{mod}$$

• It is convenient to move  $X_r$  upstream of D:

$$= B^r G^r D^r X^r P V^{mod}$$

$$(D^r = X^r D X^{r-1})$$

- **D**<sup>r</sup> is the instrumental polarization measured in the cross-hand phase frame of the gain & bandpass calibration reference antenna
- In the linear basis, X<sup>r</sup> must be determined so cross- and parallel-hands can be combined to extract correct Stokes parameters
- In the circular basis, X<sup>r</sup> is just a polarization position angle offset, which can be deferred for later external calibration

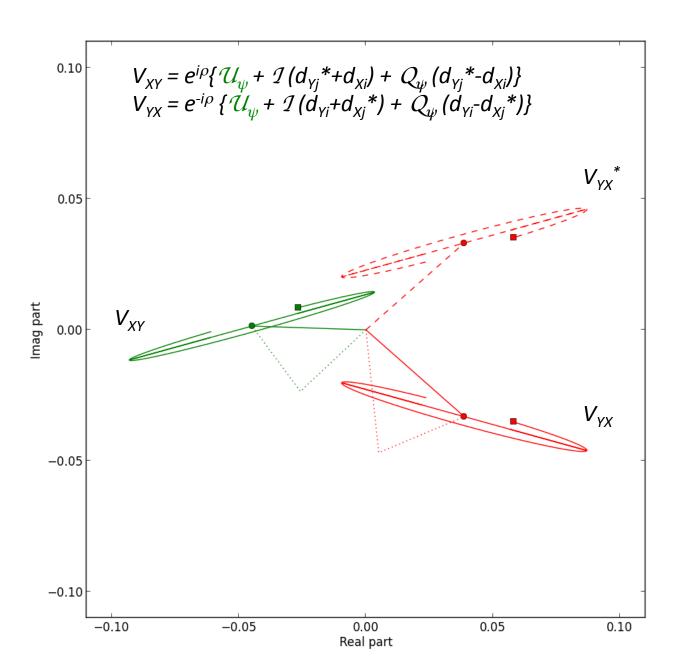
# Solving for $X^r$ and $Q_{\bullet}U$

$$(G^{r-1} B^{r-1} V^{obs}) = X^r D P V^{mod}$$

 Consider just the gain- and bandpass-calibrated cross-hands:

$$V_{XY} = e^{i\rho} \{ \mathcal{U}_{\psi} + \mathcal{I}(d_{Yj}^* + d_{Xi}) + Q_{\psi}(d_{Yj}^* - d_{Xi}) \}$$

$$V_{YX} = e^{-i\rho} \{ \mathcal{U}_{\psi} + \mathcal{I}(d_{Yi} + d_{Xj}^*) + Q_{\psi}(d_{Yi}^* - d_{Xj}^*) \}$$



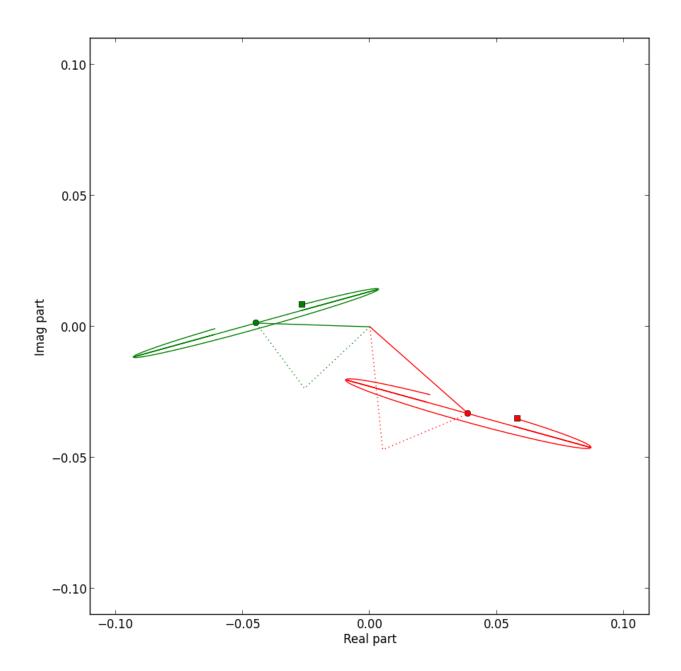
# Solving for $X^r$ and $Q_{\mathcal{U}}$ (cont)

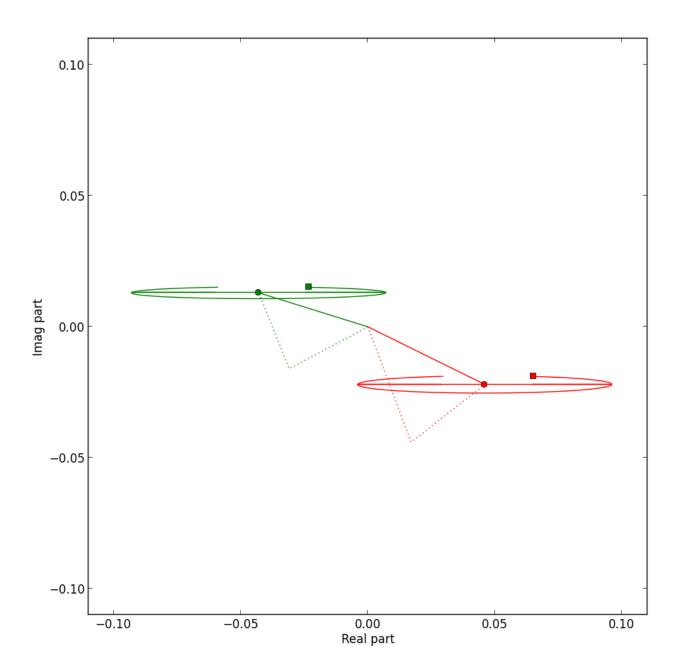
Average over baselines and correlations:

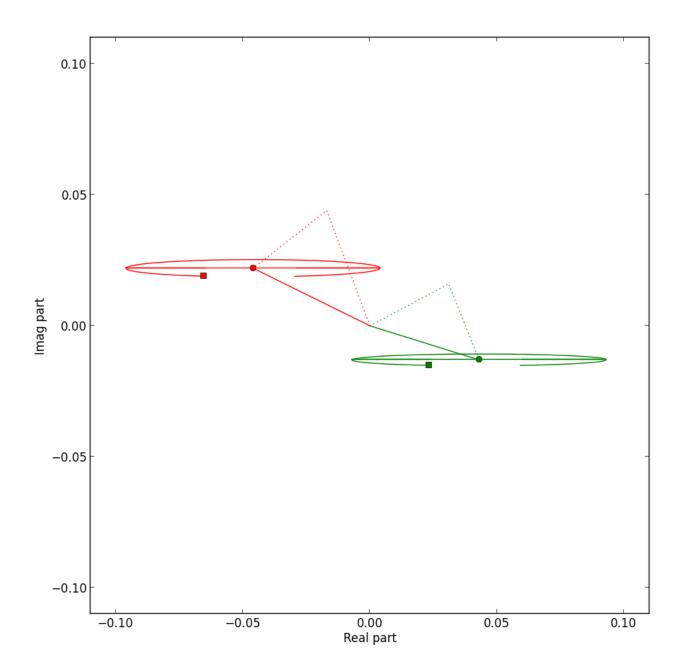
$$(\langle V_{XY} \rangle + \langle V_{YX} \rangle)/2 = \mathcal{U}_{\psi} e^{i\rho} + \langle \mathcal{I}(d_{Yj} + d_{Xi}) + \mathcal{Q}_{\psi} (d_{Yj} - d_{Xi}) \rangle e^{i\rho}$$

$$= (-Q \sin 2\psi + \mathcal{U} \cos 2\psi) e^{i\rho} + \varepsilon(t)$$

- $-\varepsilon(t)$  is small if d's are small and ~random
- Requires non-zero  $Q_{\mathcal{L}}\mathcal{U}$
- Measurements at (at least) 3 distinct  $\psi$  sufficient to determine  $\rho$ , Q,  $\mathcal{U}$ ,  $\varepsilon$ 
  - gaincal(gaintype='XYf+QU')
- Ambiguity:  $(\rho, Q, \mathcal{U}) \rightarrow (\rho + \pi, -Q, -\mathcal{U})$ 
  - Resolvable using Q,  $\mathcal U$  estimate from gain ratio: xyamb
- Requires  $X^r$  stability: a "good" refant for gain and bandpass (c.f.  $|g_X|$   $g_Y$  stability expectations)
- ATCA (linears) use a calibration signal to monitor X<sup>r</sup>
  - refant operation in  $G^r$  and  $B^r$  solves will then merely enforce the truth)







### D

- Frequency-dependent D solution ( $Q_{\psi}d$ -sensitive): polcal(poltype='Dflls')
- Sky frame D: dxy
  - Rotate out of gain refant cross-hand phase frame:
    - $D = (X^{r-1} D^r X^r)$
  - Continuity over spectral windows
  - Appropriate frame for 'canned' D (not tied to a specific gain refant)
- General matrix correction: Dgen
  - Relabeling to enforce full matrix correction

# **Additional Topics**

- Solving for **D** (linear basis): Unpolarized vs.
   Polarized Calibrator?
- Multi-field solution?
- Stokes  $\mathcal{V}$ ?
- 'Canned' **D**?
- Poorly-optimized optics?

# Solving for **D** (linear basis)

- Unpolarized source, single scan?
  - Simple, but d's are degenerate, to first order:

$$V_{XY} = \mathcal{I}(d_{Yj}^* + d_{Xi}) = \mathcal{I}[(d_{Yj}^- - a)^* + (d_{Xi}^+ + a^*)]$$

- for any complex number a
- Therefore, one d remains effectively unconstrained
- Standard convention is to apply a reference antenna that effectively enforces  $a = -d_{Xref}^*$ :

$$d_{xi} \rightarrow (d_{Xi} + a^*)$$
  $d_{Yi} \rightarrow (d_{Yi} - a)$  (for all i)

- These referenced d's correct the data to some orthogonal (to first order) basis that is defined by the refant's true  $d_x$ -- but not a pure one
- Position angle calibration satisfies refant's real part
  - Imag part (ellipticity registration)?

# Solving for **D** (linear basis)

- Polarized (known) source, single scan ( $\psi = const$ )?
  - Still degenerate in linear cross-hands (incl.  $Q_{\psi}$  terms):

$$V_{XY} = \mathcal{U}_{\psi} + (\mathcal{I} + Q_{\psi})d_{Yj}^* + (\mathcal{I} - Q_{\psi})d_{Xi}$$
  
=  $\mathcal{U}_{\psi} + (\mathcal{I} + Q_{\psi})(d_{Yj} - b)^* + (\mathcal{I} - Q_{\psi})(d_{Xi} + c^*)$ 

• for any complex numbers b, c satisfying

$$b = c(\mathcal{I} + Q_{\psi})/(\mathcal{I} - Q_{\psi})$$

- Incorrectly calibrates data with different  $Q_{\psi}$  (other times, sources)
- If  $Q_{\psi}d$  terms ignored, same as unpolarized source case

# Solving for **D** (linear basis)

- Polarized source w/ parallactic angle coverage
  - Multiple, non-zero  $Q_{\psi}$  breaks degeneracies
  - Depends on time stability of D
    - also required/assumed for accurate transfer to other sources
  - Resulting solution accuracy limited by:
    - accuracy of calibrator model's Q, U, V
    - systematic bias (if any) in assumed feed position angle setting (if  $Q\mathcal{U}$  derived from data)
    - systematic biases (if any) originating in 2<sup>nd</sup>-order terms

### Multi-field **D** solution?

- Each new source adds 2 unknowns, with insufficient additional constraints to determine them
  - Still need at least one source with sufficient parallactic angle coverage
- VLBI (circular basis) leverages differential parallactic angle variation to constrain 'absolute' D
  - ALMA is a 'small array' with practically uniform parallactic angle across the array

### Stokes $\mathcal{V}$ ?

- Spectral line (e.g., Zeeman)
  - Enabled by detecting specified spectral signature relative to arbitrary background "continuum/ systematic" level, which is fit for but ignored

#### Continuum

- Effectively unconstrained without *absolute*  $\mathcal{V}$  reference
- Statistical constraint: universe has no preferential handedness (e.g., ATCA: Rayner et al., 2000)

### 'Canned' **D**?

- Yes, if reliably stable!
  - In CASA:
    - Requires formal recognition of 'sky-frame' D's in the internal calibration model (TBD)
    - Requires look-up mechanism (c.f. antenna-position corrections, etc.)
    - General matrix algebra?
  - At ALMA (and EVLA): Requires measuring it adequately (incl. frequency coverage at sufficient resolution)
    - Updates required at RX 'events' (c.f. antenna-position corrections when telescopes move)
  - Natural extension of beam polarization models?
    - Add, don't multiply!
    - Not as simply modeled, probably?

### Non-optimized optics?

- Effect of poor feed mount collimation?
- Vertex astigmatism?
- Effect of tilt-less sub-reflector?
  - Primary optics effectively asymmetric
  - (c.f. beam models?)
- Coupled effects, e.g. focus and pointing models are deliberate time-dependent perturbations on the optics
- 'Forward' polarization-dependent gain effects?
- > Effects on **D** and its stability?

## **CASA Planning**

- The following is George's personal view
- NB: All polarization development plans must be evaluated and prioritized alongside general CASA development cycle planning
  - V4.4 development underway; release: ~Apr 2015
  - V4.5 planning beginning now; release: ~Oct 2015
- Pipeline context...

### CASA Todo List - I

- Algorithm/Robustness Improvements
  - Position angle calibration for linear basis (needed for unpolarized D calibrator case)
    - Ellipticity registration calibration?
  - Support "Sky-frame" D in general apply
    - Enables canned D
  - -QU model storage/usage (MS.SOURCE) to streamline processing
    - Eases migration of most almapolhelpers.py functionality into standard CASA tasks
  - qufromgain: option to remove source polarization signal from gains
    - Also detect/remove antennas with outlying gain ratios; antenna (de-)selection?
  - Iteration packaging (has been deliberately 'naked', for now, but only minimally explored so far)
- Modularization
  - Separate (optionally) XY-phase and QU estimation
    - Ad hoc XY-phase ambiguity switch (gencal)
  - Migrate 'Xyf+QU' functionality from gaincal to polcal

### CASA Todo List - II

- Improve Documentation!
  - CASAguide by Rosita
  - Memos
- Visualization
  - Viewer enhancments (e.g., simplified vector plotting)
  - Stokes options in plotms (flagging?)
- Simulation
  - Corruption by full magnitude instrumental polarization
  - Corruption by plausible residual instrumental polarization (so as to yield realistically 'poor' result)