

Short intro to interferometry

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IT-ARC

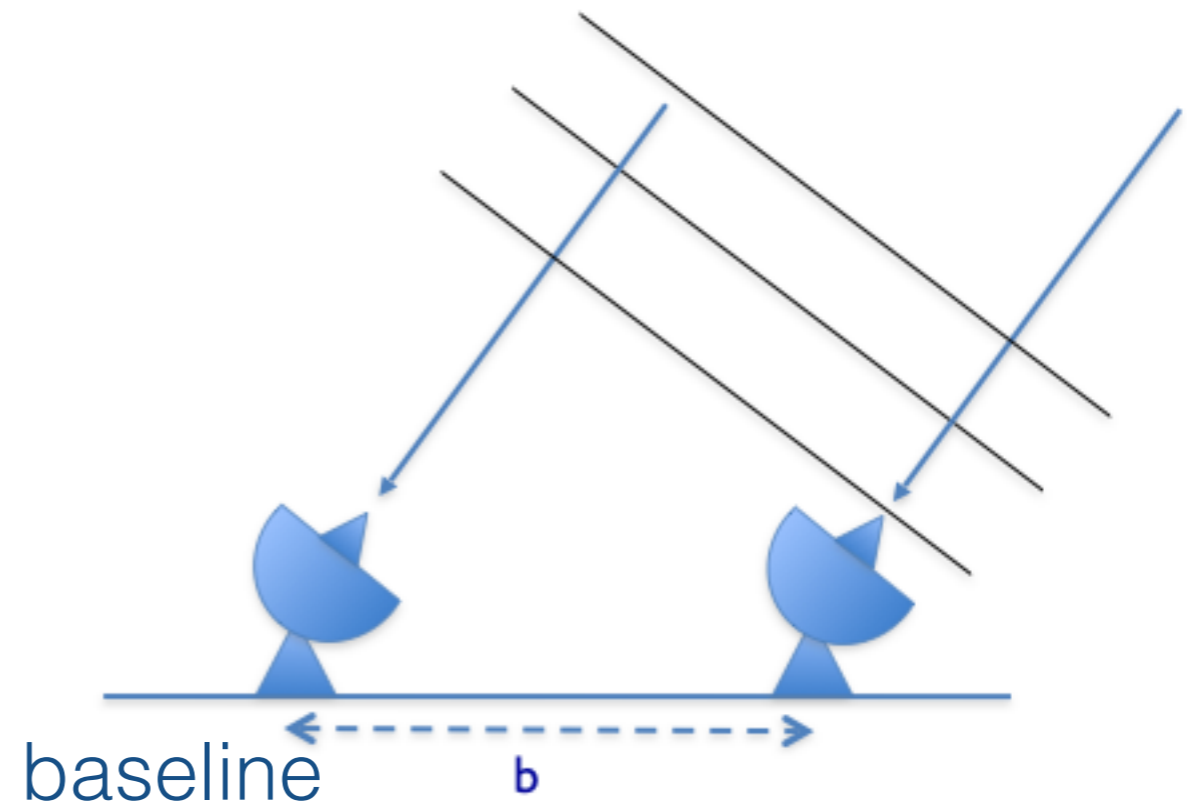
Outline

- Interferometry (the basics)
- Visibility and sky brightness
- how should I *use* ALMA archival data:
 - my scientific goal overlaps what that specific ALMA observation may offer?
- some definition (Flux, Beam, Sensitivity, data cube...)

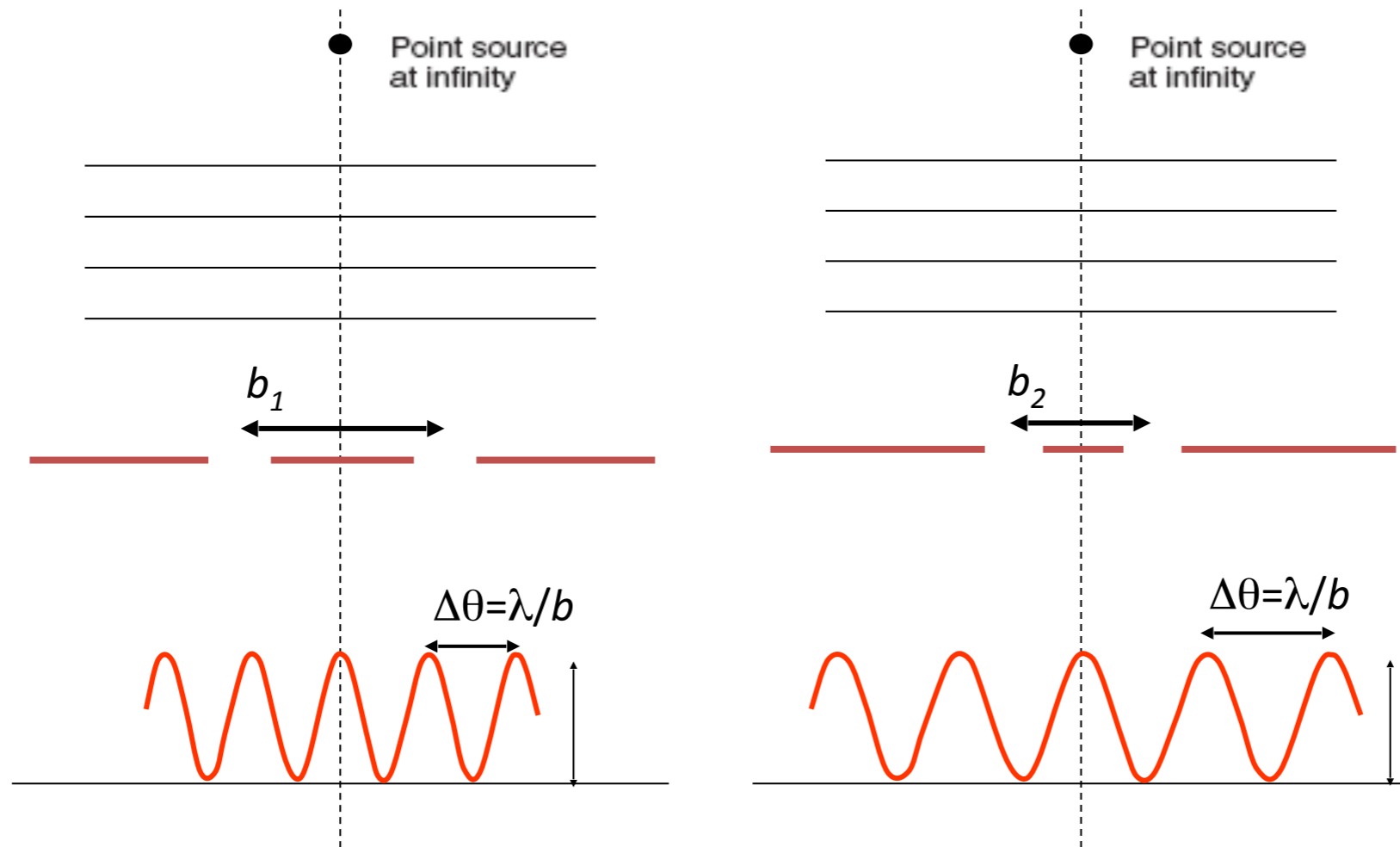
AIM: not to explain interferometry in detail, but make users more conscious when using Archive Data

Interferometers: the basics

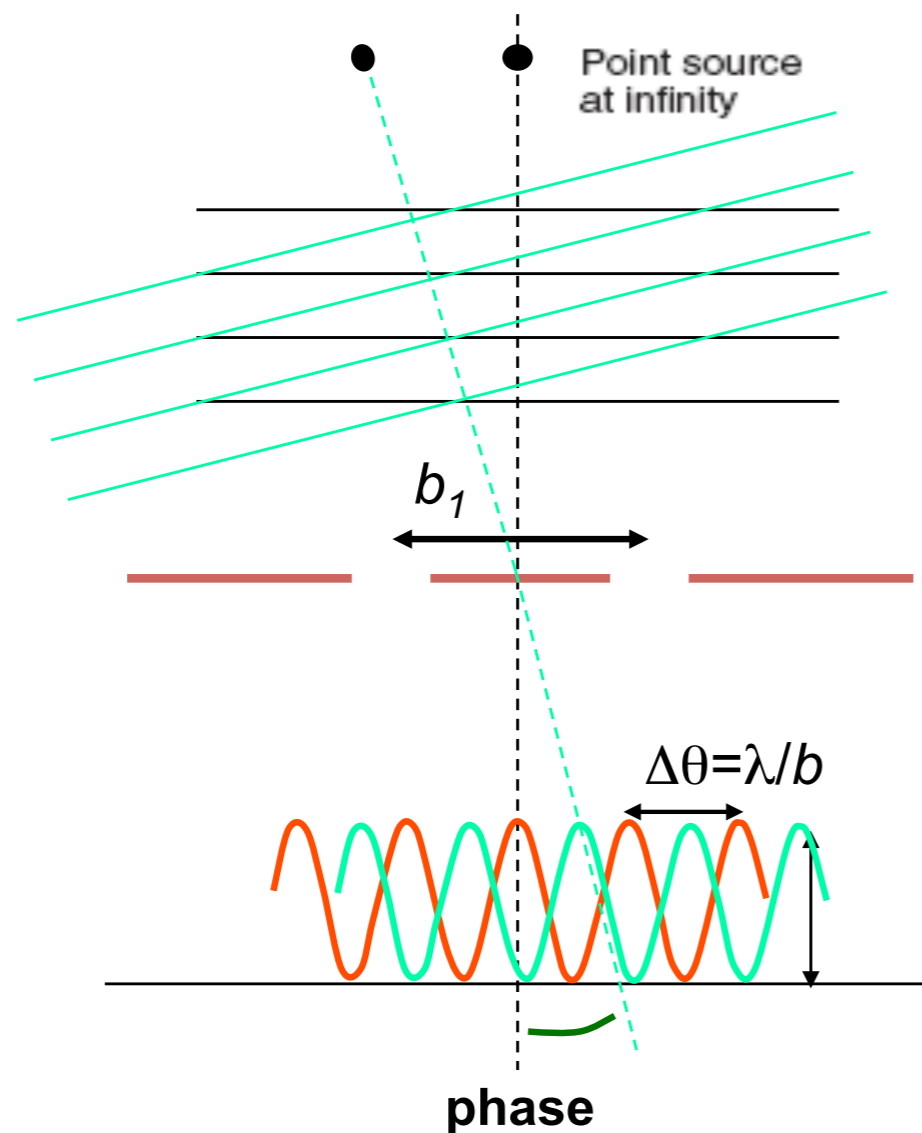
- Interferometry: a method to 'synthesize' a large aperture by combining signals collected by separated small apertures
- An Interferometer measures the interference pattern produced by two apertures, which is related to the source brightness.
- The signals from all antennas are correlated, taking into account the distance (baseline) and time delay between pairs of antennas



Interferometers: the basics



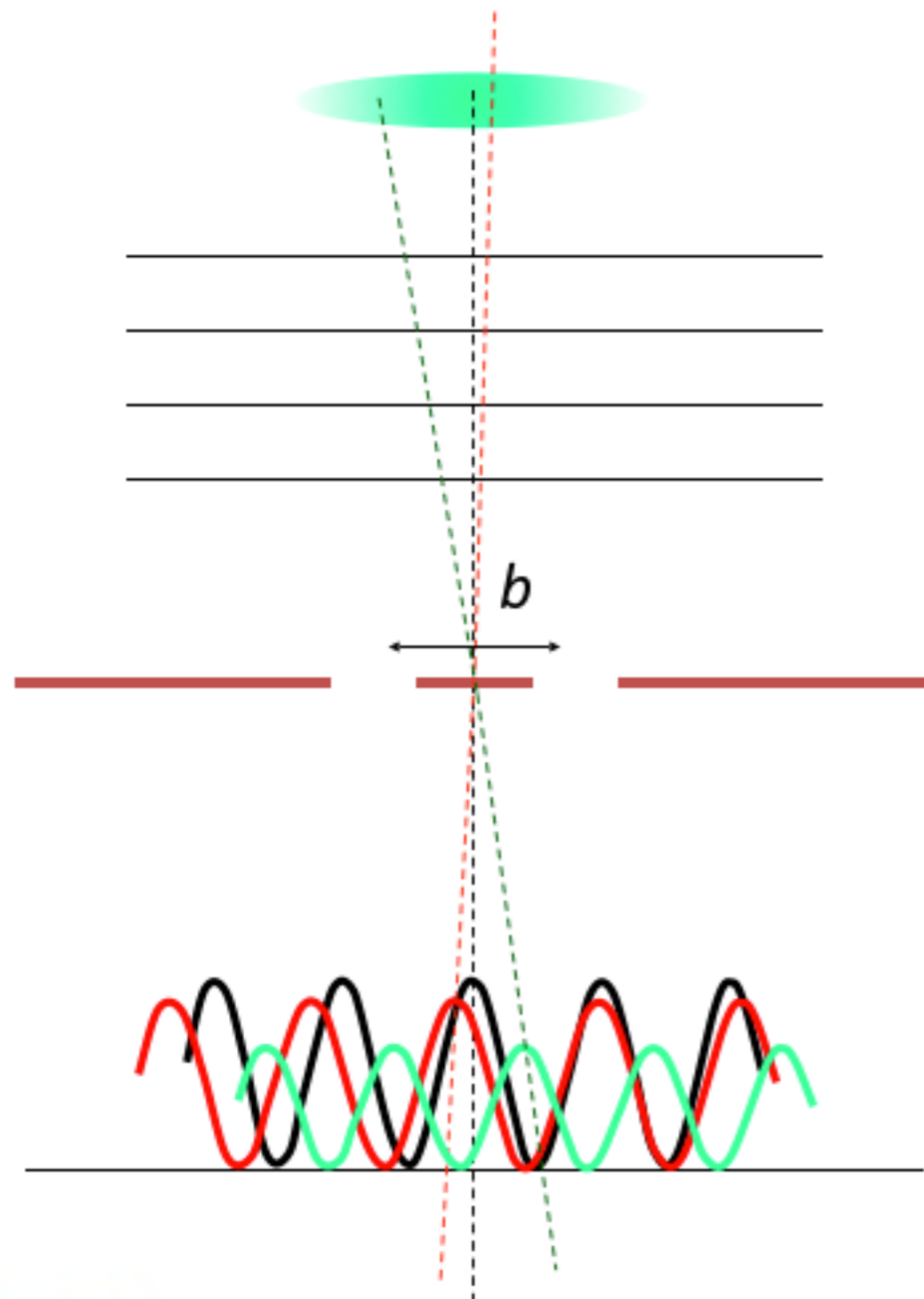
Interferometers: the basics



Spatial Frequency λ/b

if we observe at different λ ,
we sample different spatial
frequencies

Interferometers: the basics



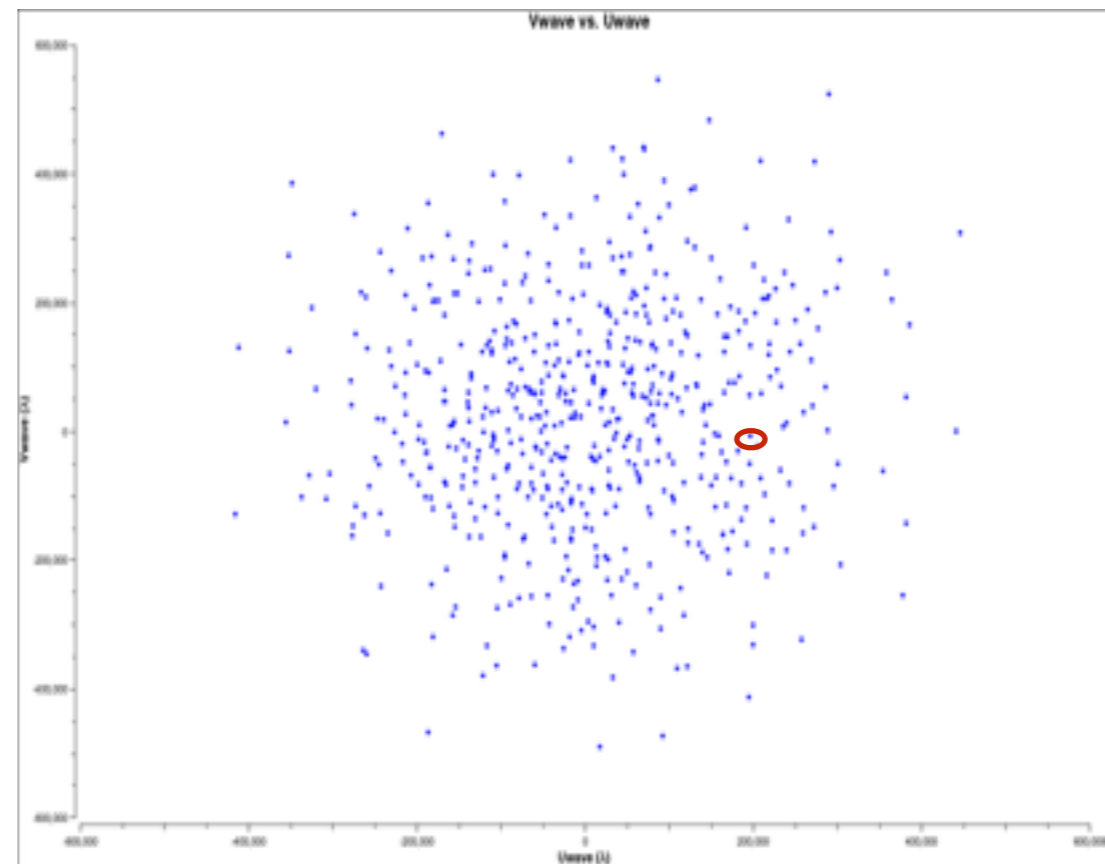
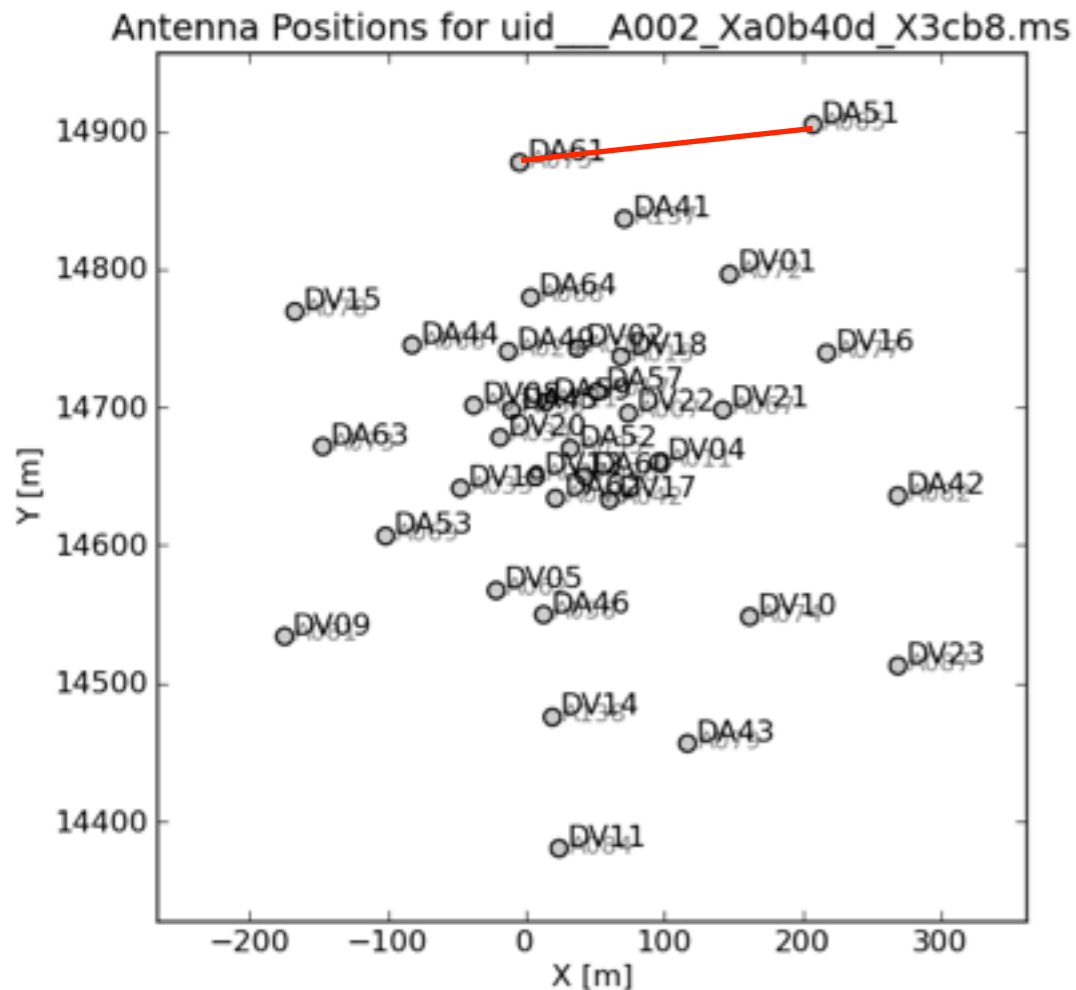
- Amplitude tells “how much” of a certain frequency component
- Phase tells “where” this component is located



Visibility

Interferometers: the baseline in the uv plane

each antenna pair \rightarrow a point in uv plane



$b(u,v)$ in λ units

u, v components in the E-W, N-S directions

Visibility and Sky Brightness

For small fields of view: the complex visibility, $V(u,v)$, is the 2D Fourier transform of the brightness on the sky, $T(x,y)$

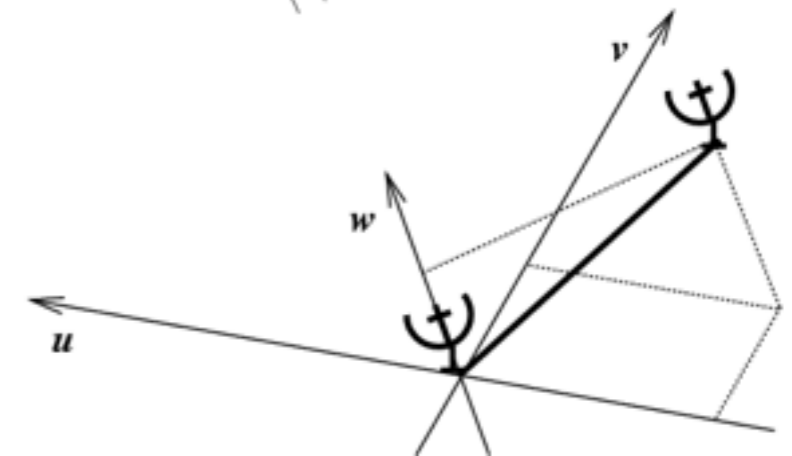
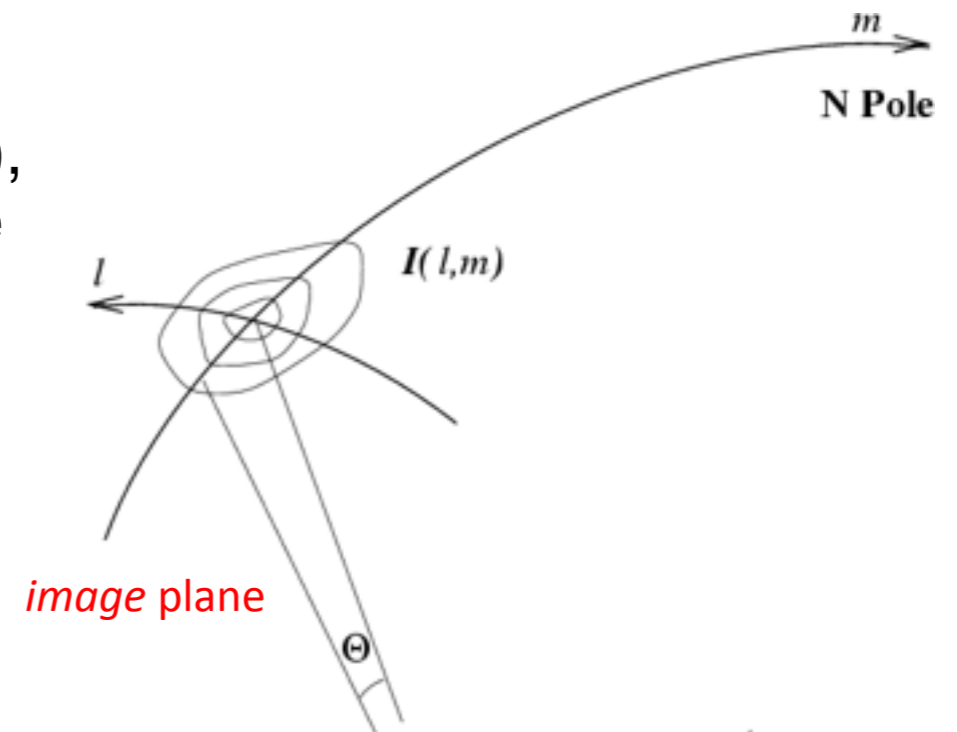
Cittert-Zernike theorem

$$V(u, v) = \iint T(x, y) e^{2\pi i(ux+vy)} dx dy$$

$$T(x, y) = \iint V(u, v) e^{-2\pi i(ux+vy)} du dv$$

- u, v (wavelengths) are spatial frequencies in E-W and N-S directions, i.e. the baseline lengths
- x, y (rad) are angles in tangent plane relative to a reference position in the E-W and N-S directions

$$V(u, v) \rightleftharpoons T(x, y)$$



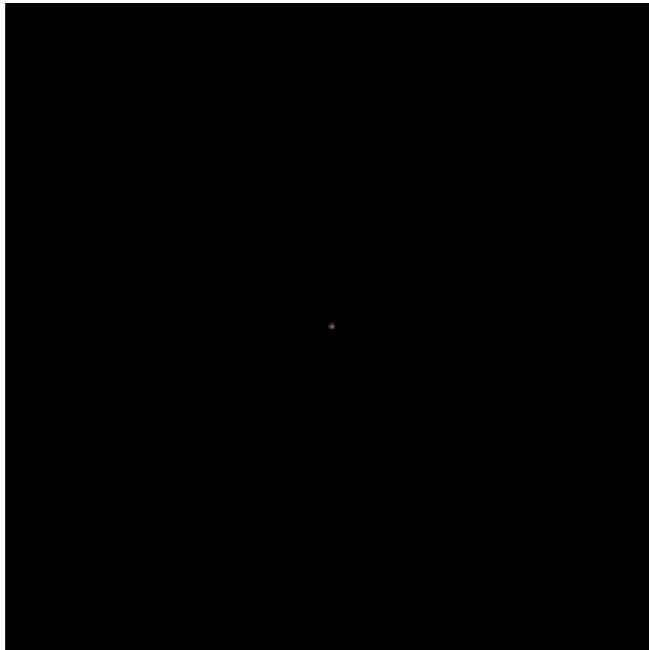
uv plane

2D Fourier Transforms

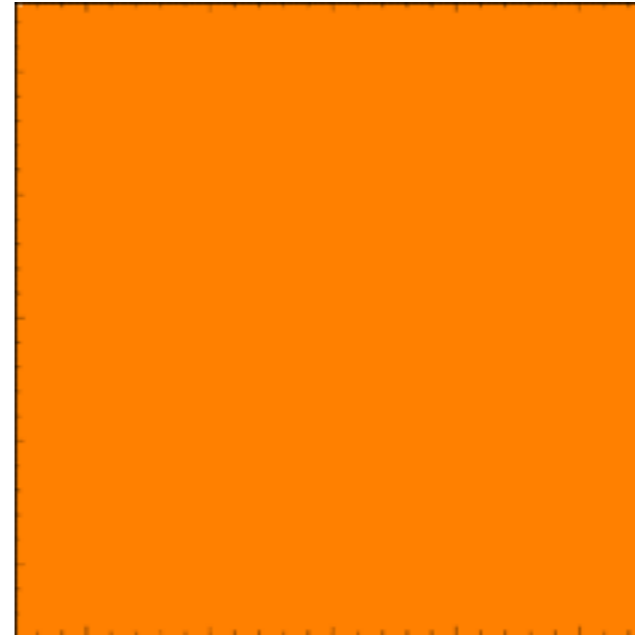
$T(x,y)$

$\text{Amp}\{V(u,v)\}$

δ Function

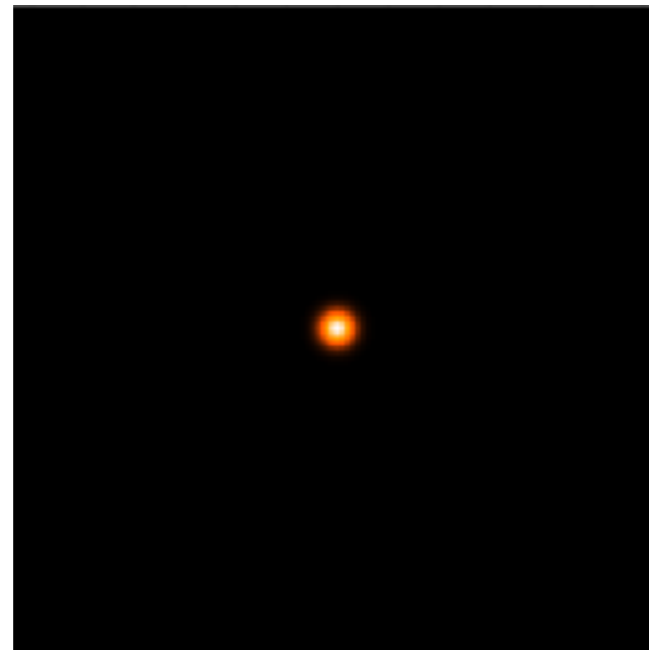


\Downarrow



Constant

Gaussian



\Downarrow



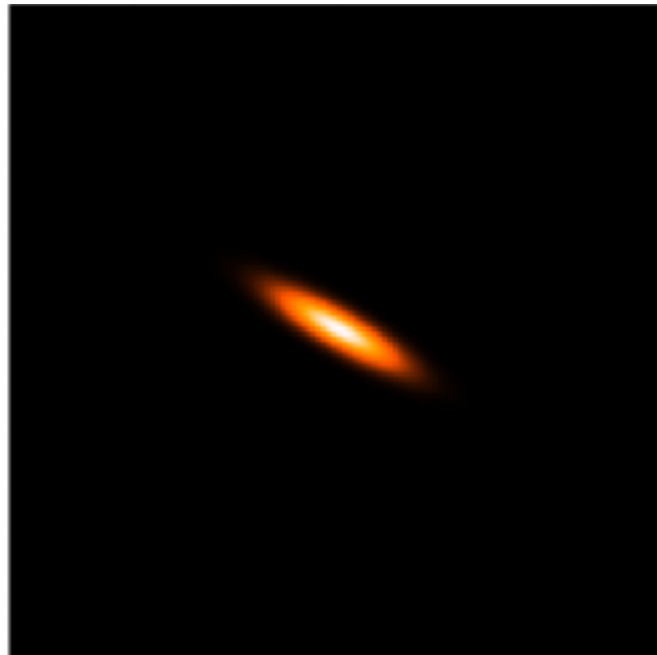
Gaussian

narrow features transform to wide features (and vice-versa)

2D Fourier Transforms

$T(x,y)$

elliptical
Gaussian



\Downarrow



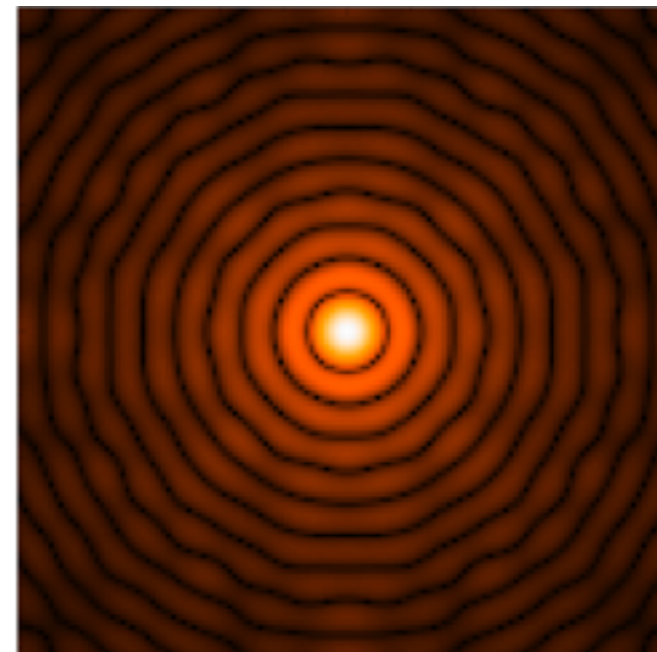
$\text{Amp}\{V(u,v)\}$

elliptical
Gaussian

Disk



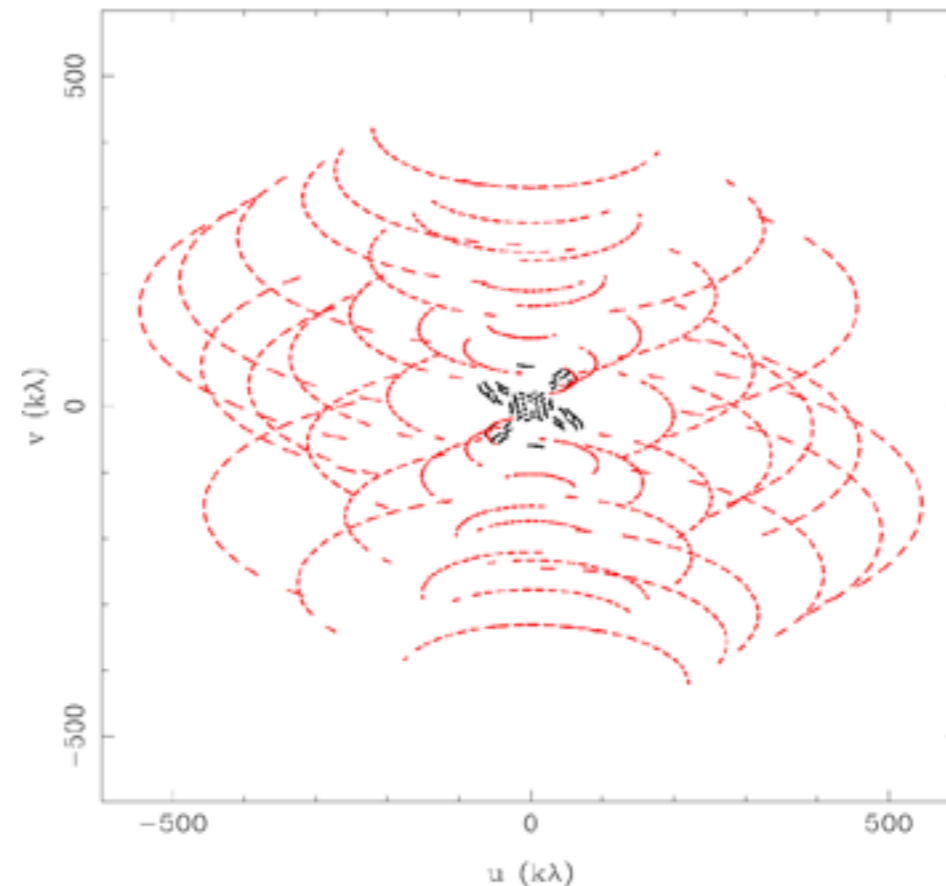
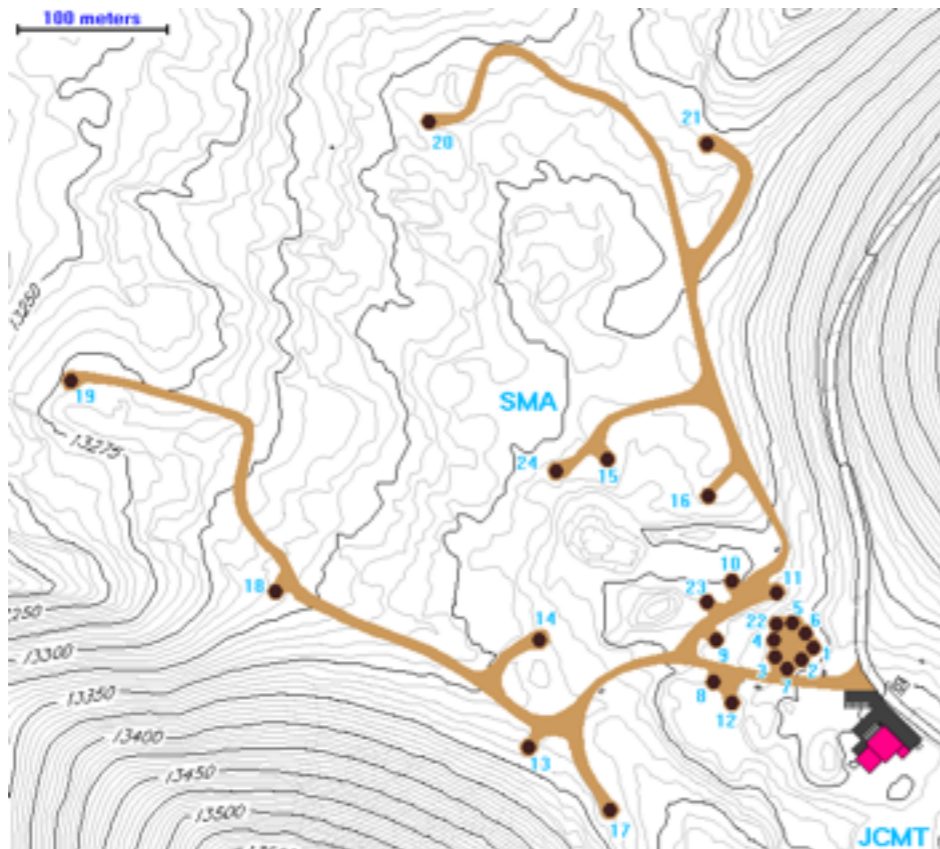
\Downarrow



Bessel

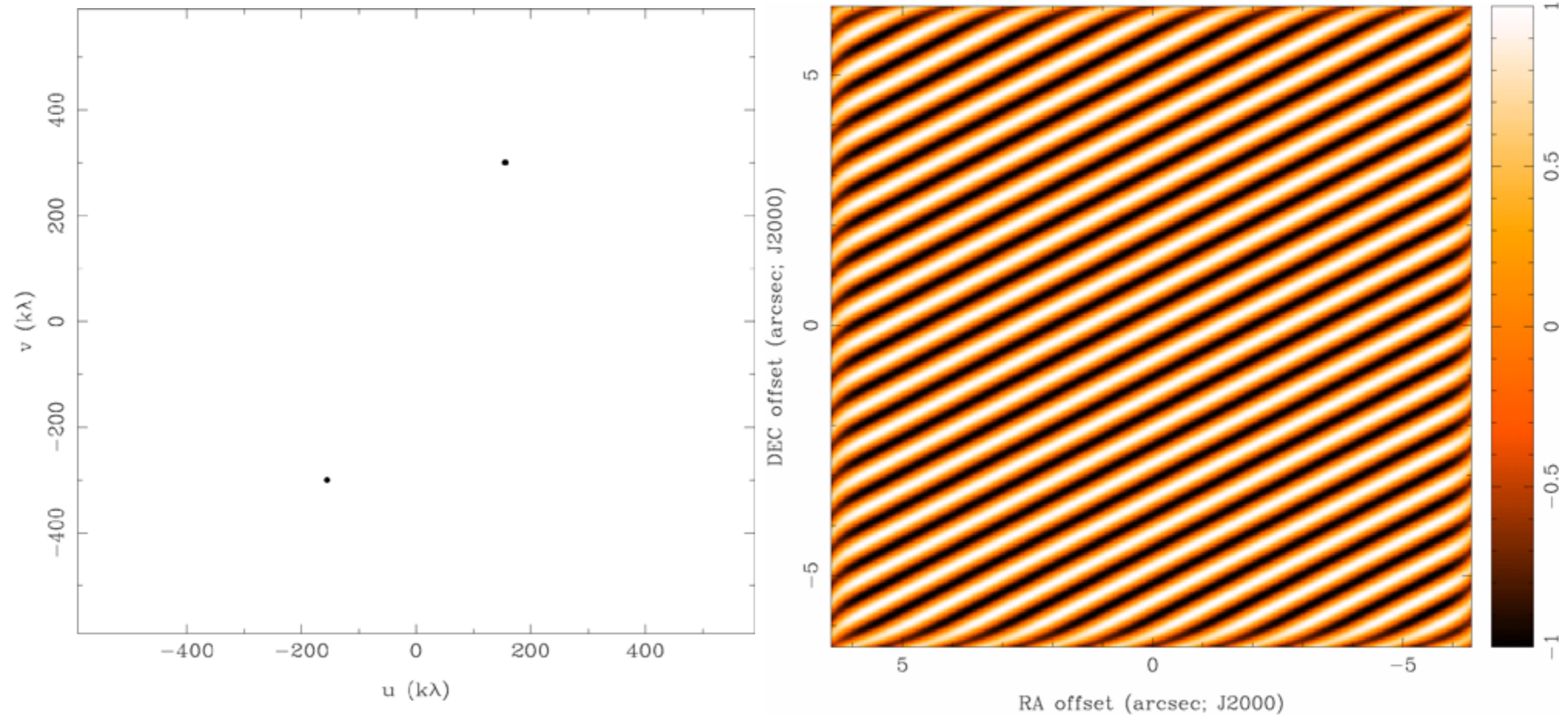
Aperture Synthesis

- Sample $V(u,v)$ at enough points to synthesis the equivalent large aperture of size (u_{\max}, v_{\max})
 - 1 pair of telescopes \rightarrow 1 (u,v) sample at a time
 - N telescopes \rightarrow number of samples = $N(N-1)/2$
- A good image quality requires a good coverage of the uv plane
 - fill in (u,v) plane by making use of Earth rotation (“track”)
 - reconfigure physical layout of N telescopes



PSF shape vs. N ants

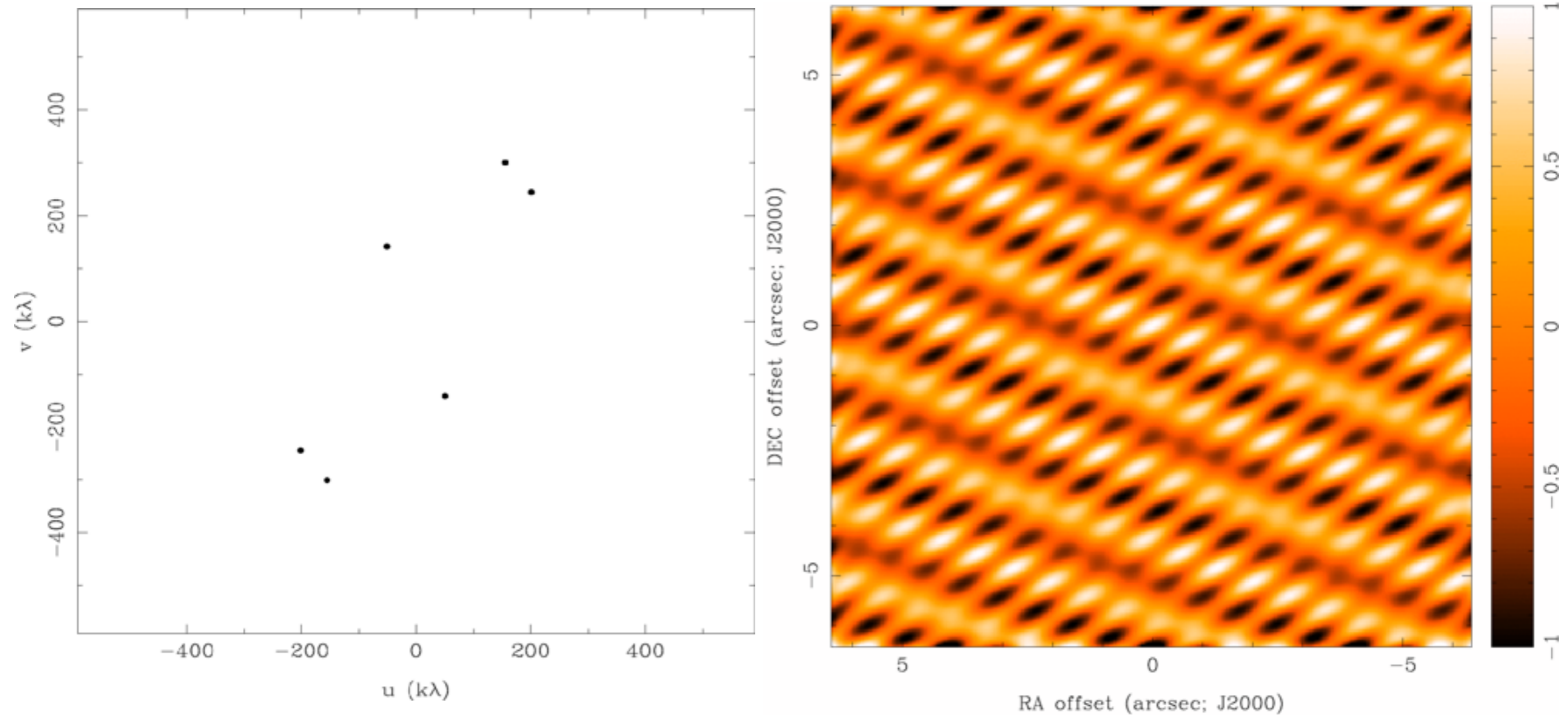
2 antennas



- to characterize a source, I need to sample as much as possible the uv plane.

PSF shape vs. N ants

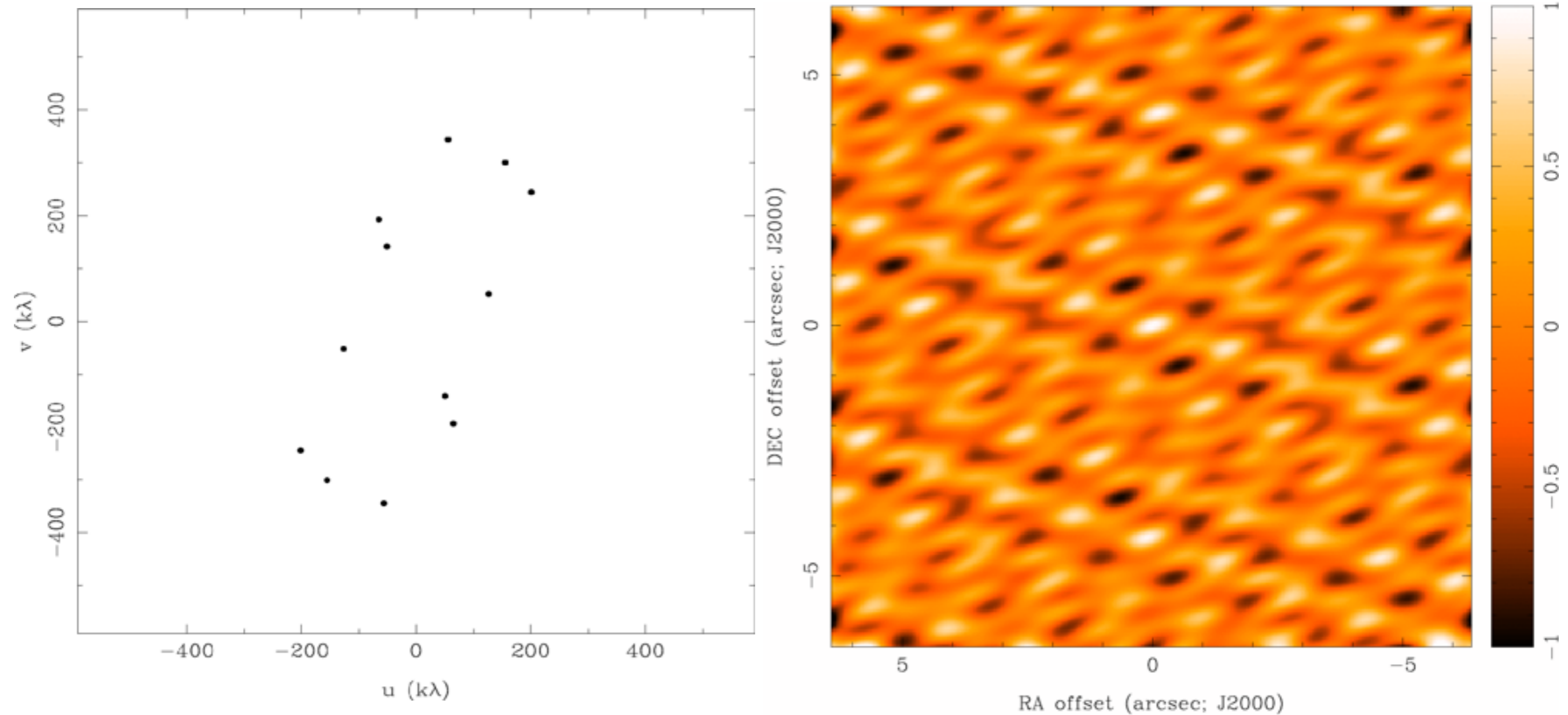
3 antennas



by increasing the number of antennas ...

PSF shape vs. N ants

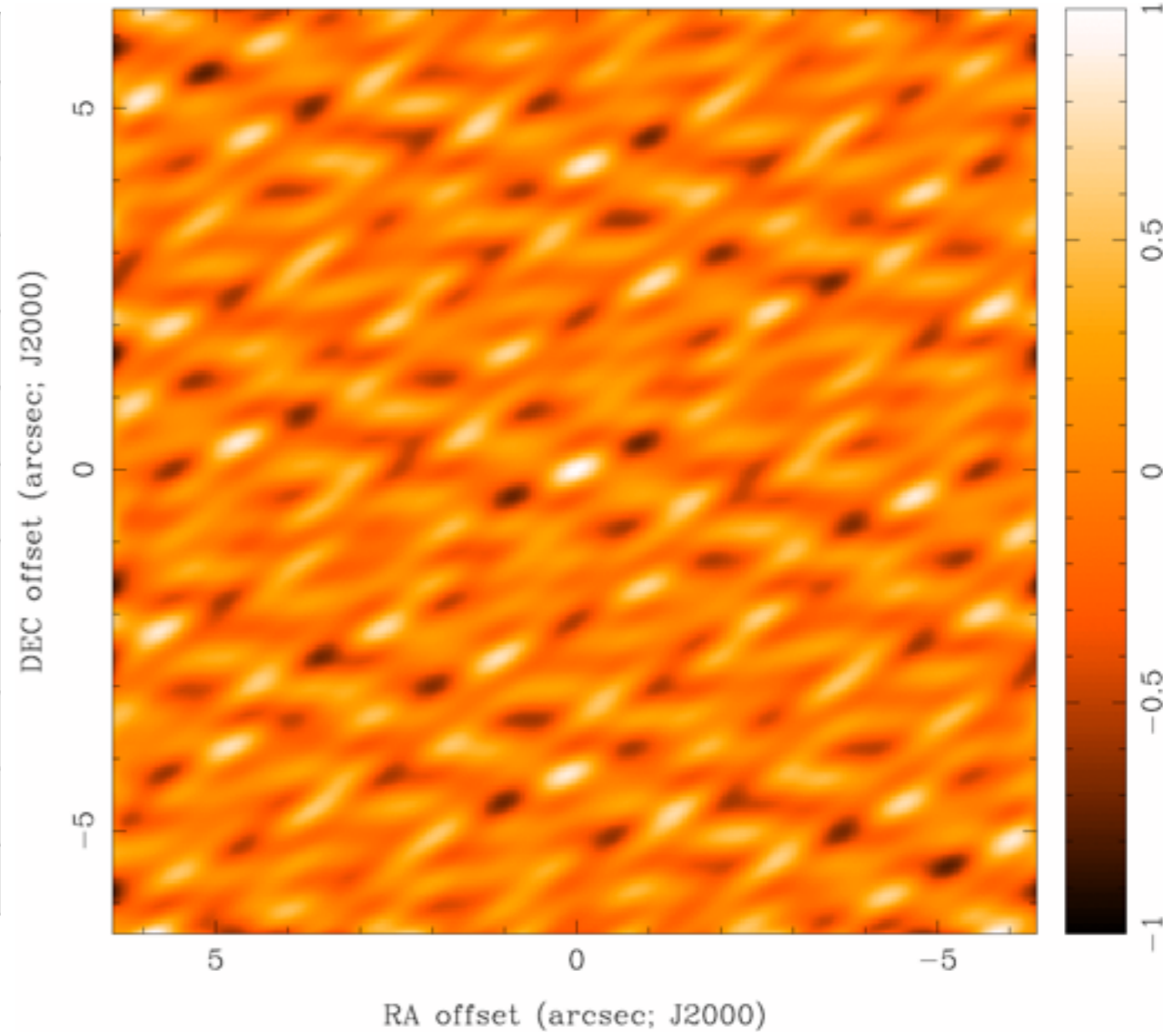
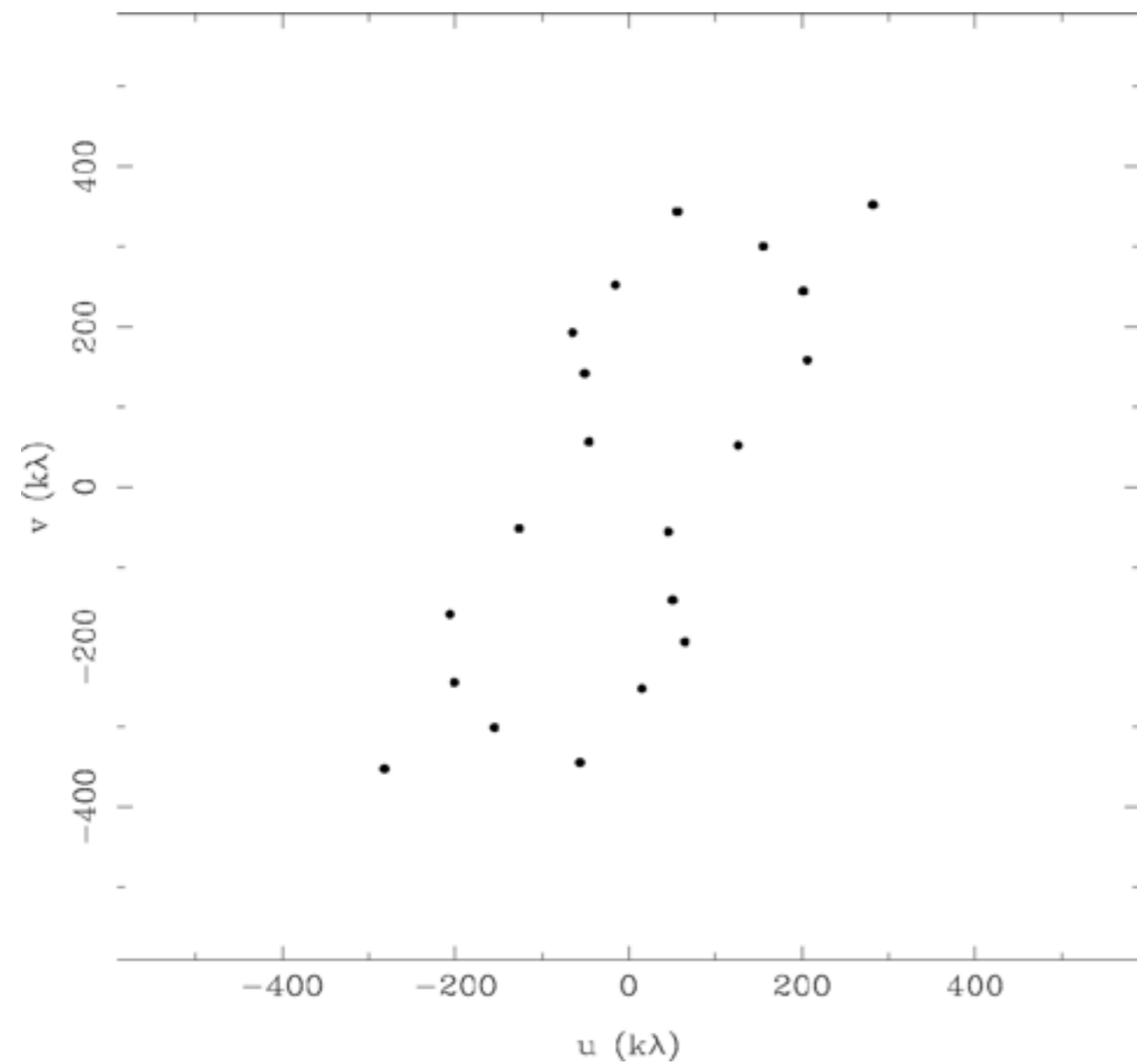
4 antennas



by increasing the number of antennas ...

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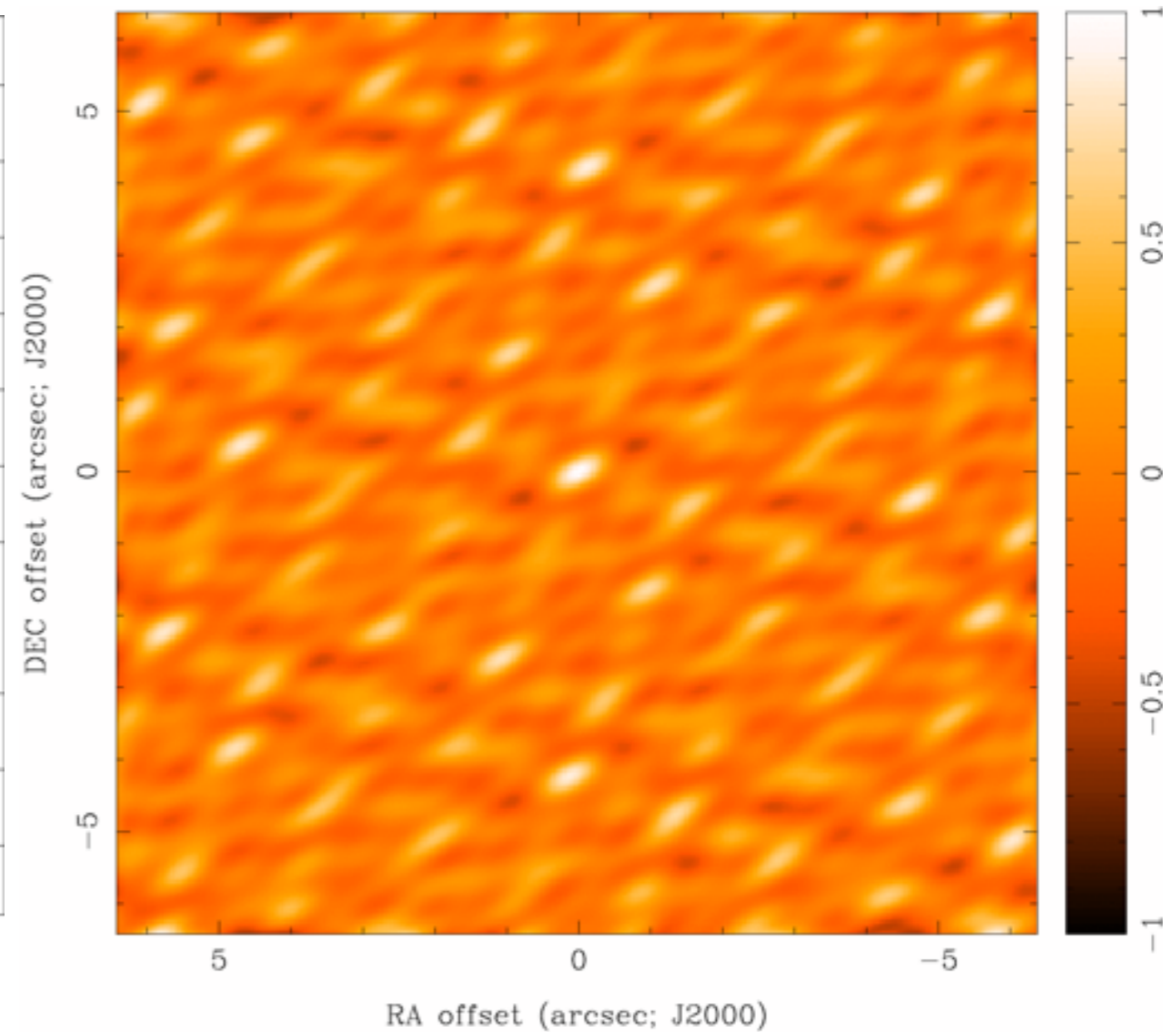
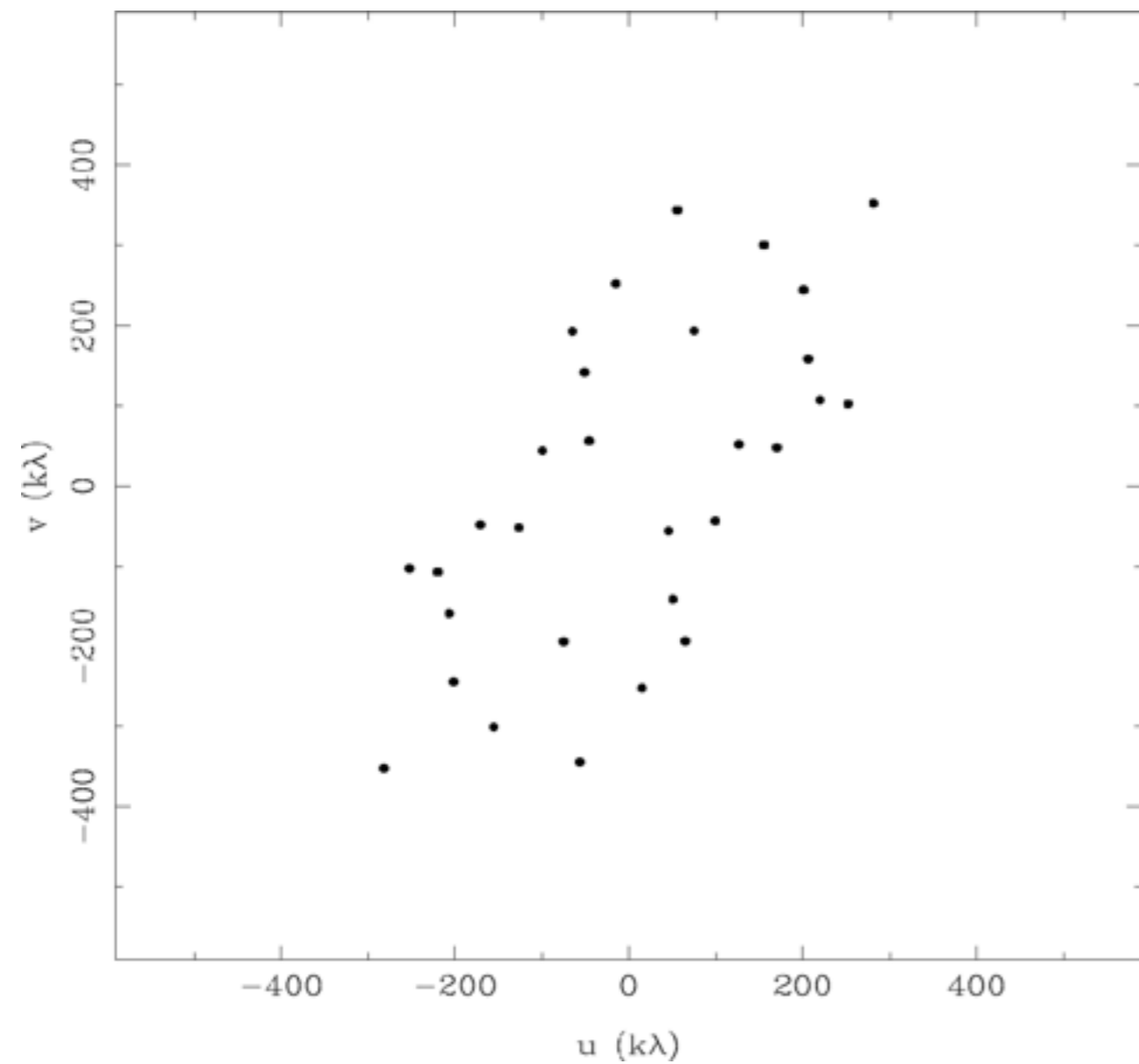
5 antennas



by increasing the number of antennas ...

PSF shape vs. N ants

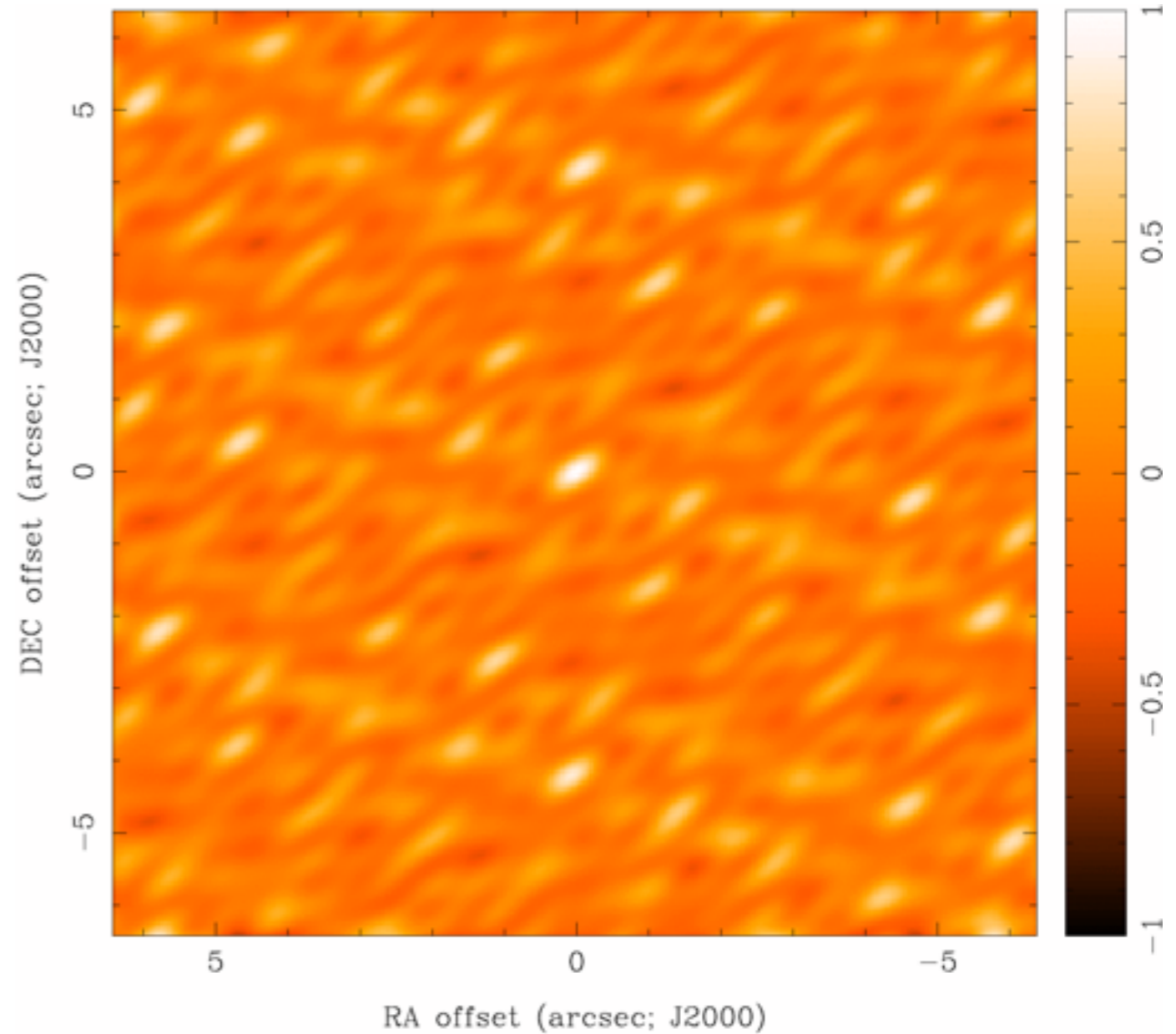
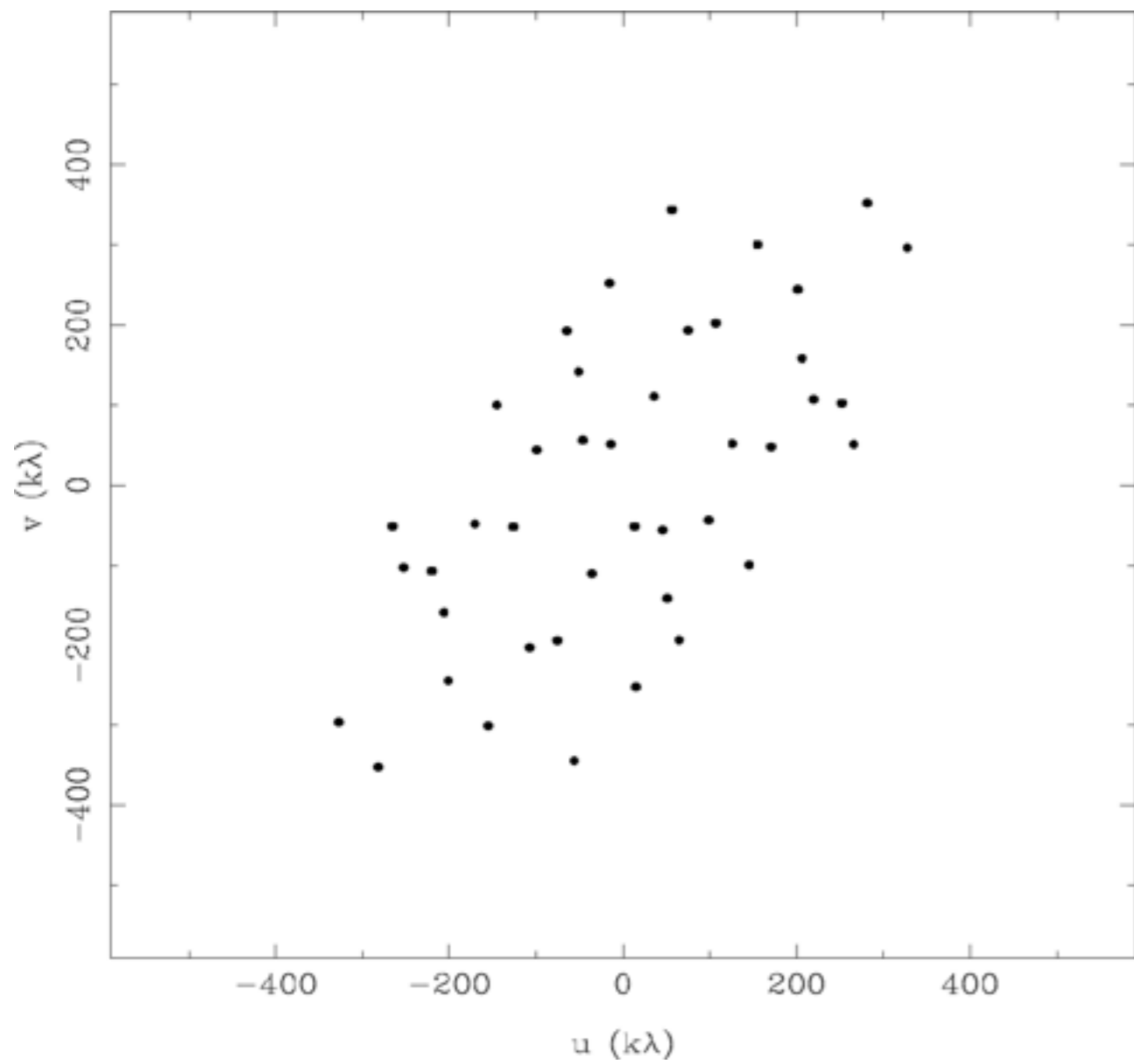
6 antennas



by increasing the number of antennas ...

PSF shape vs. N ants

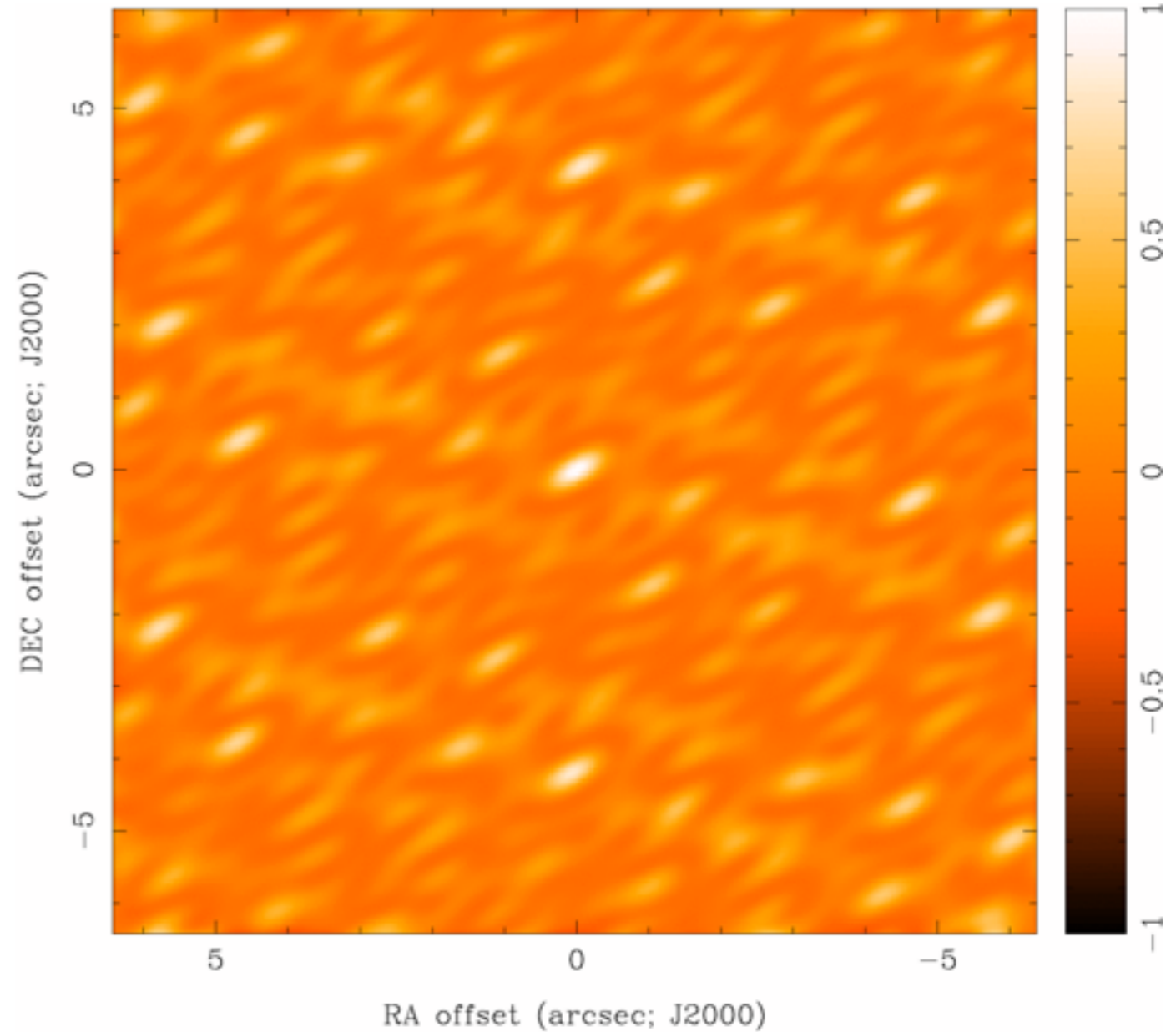
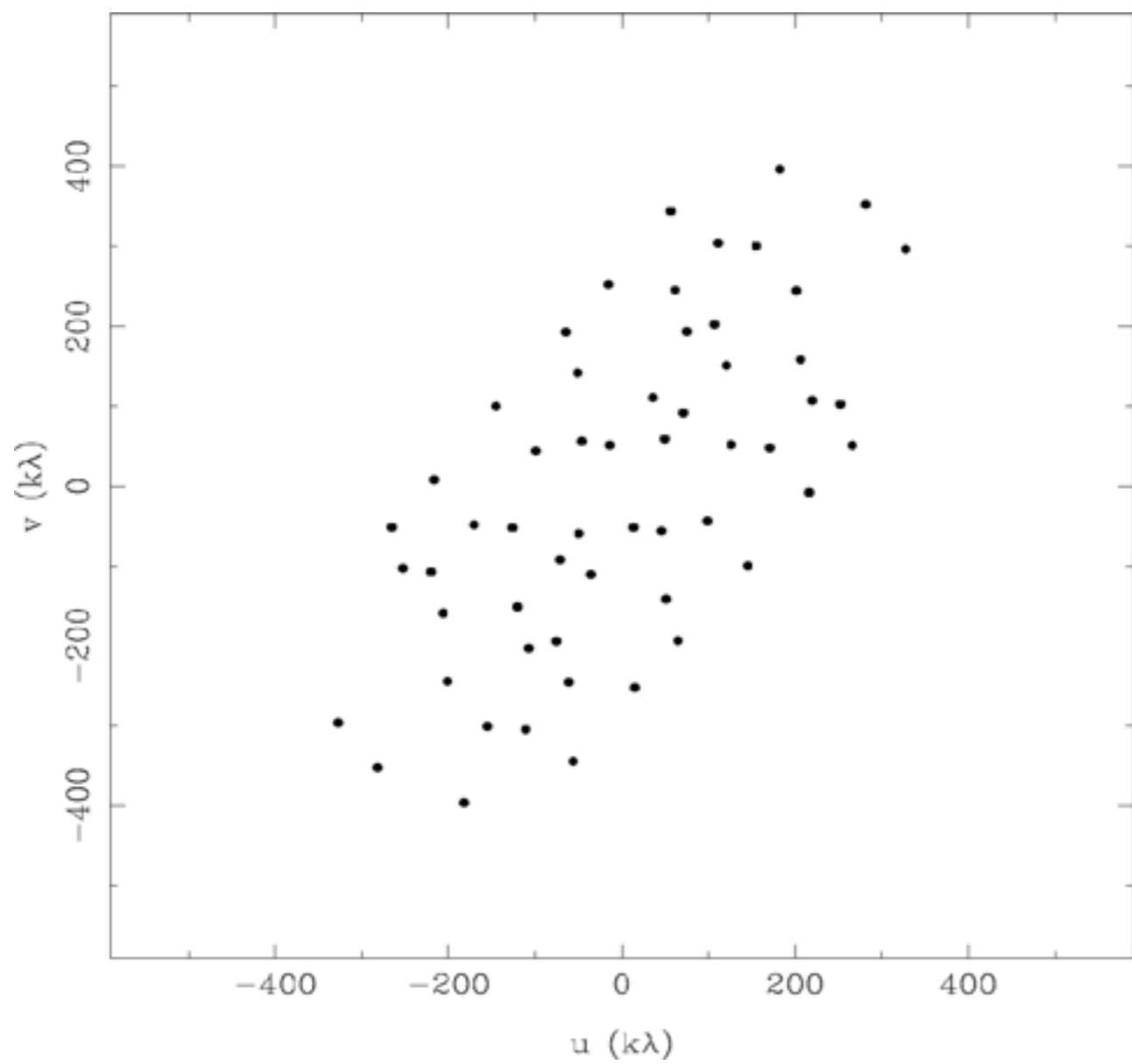
7 antennas



by increasing the number of antennas ...

PSF shape vs. N ants

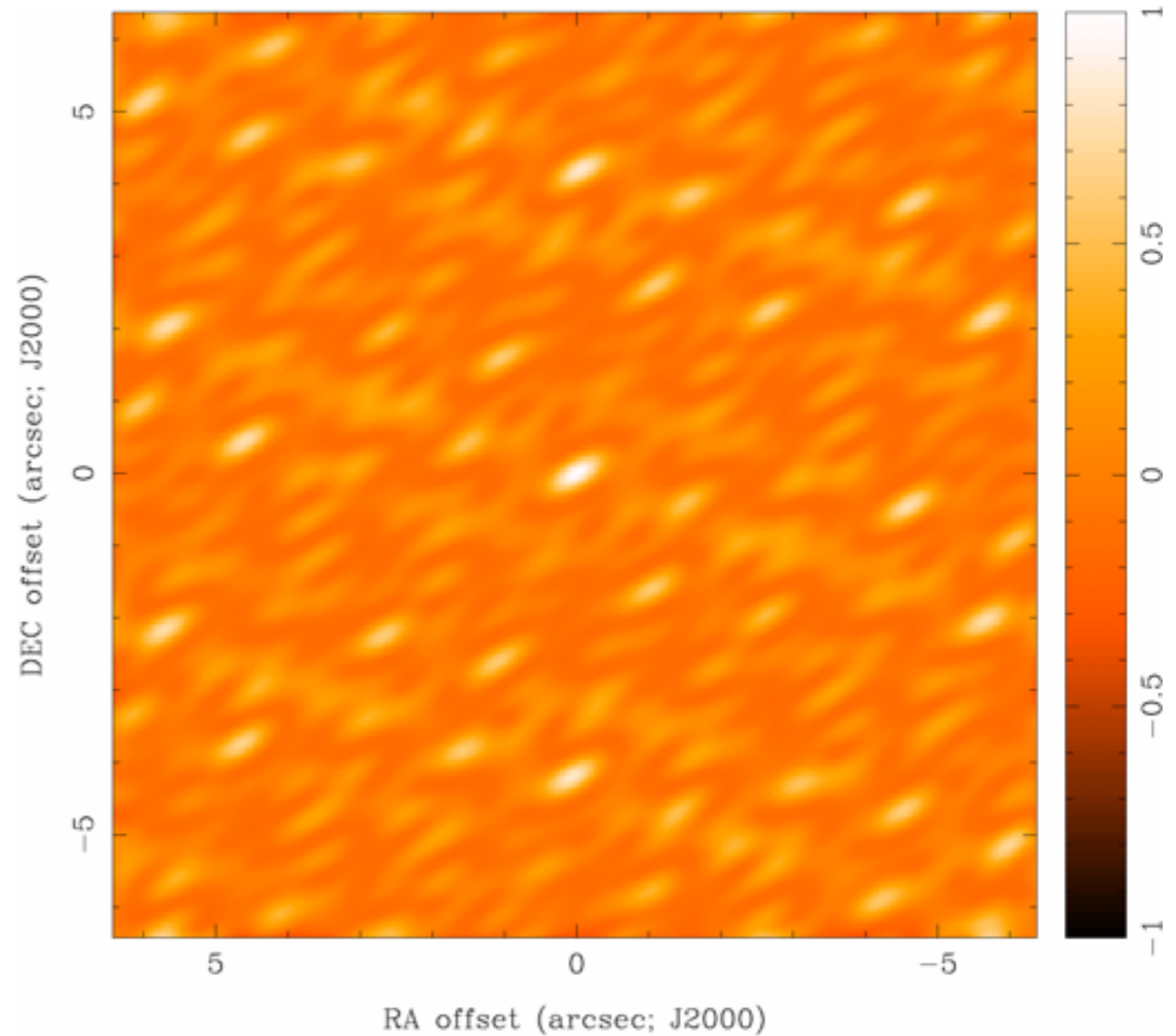
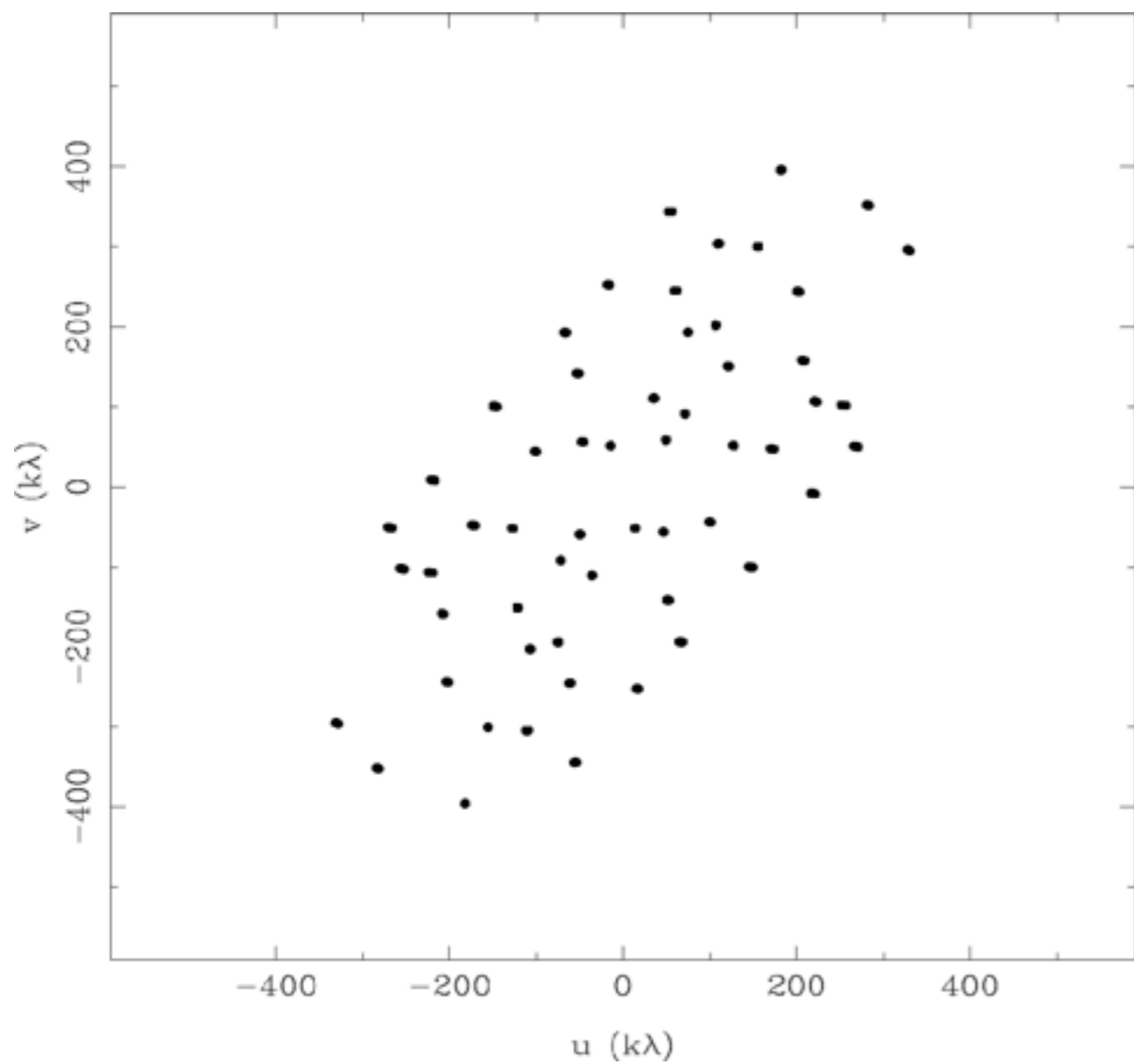
8 antennas



by increasing the number of antennas ...

PSF shape vs. N ants

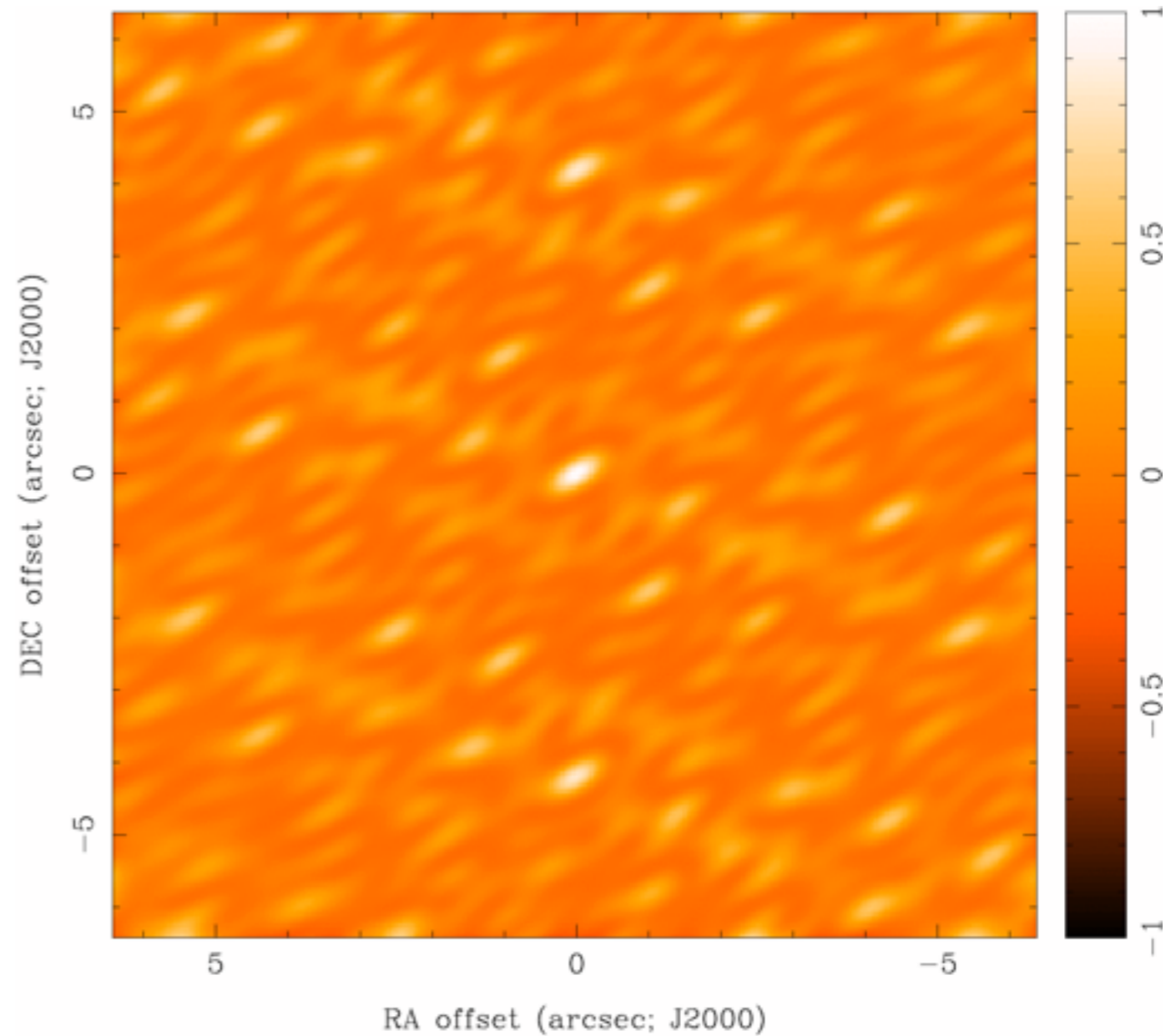
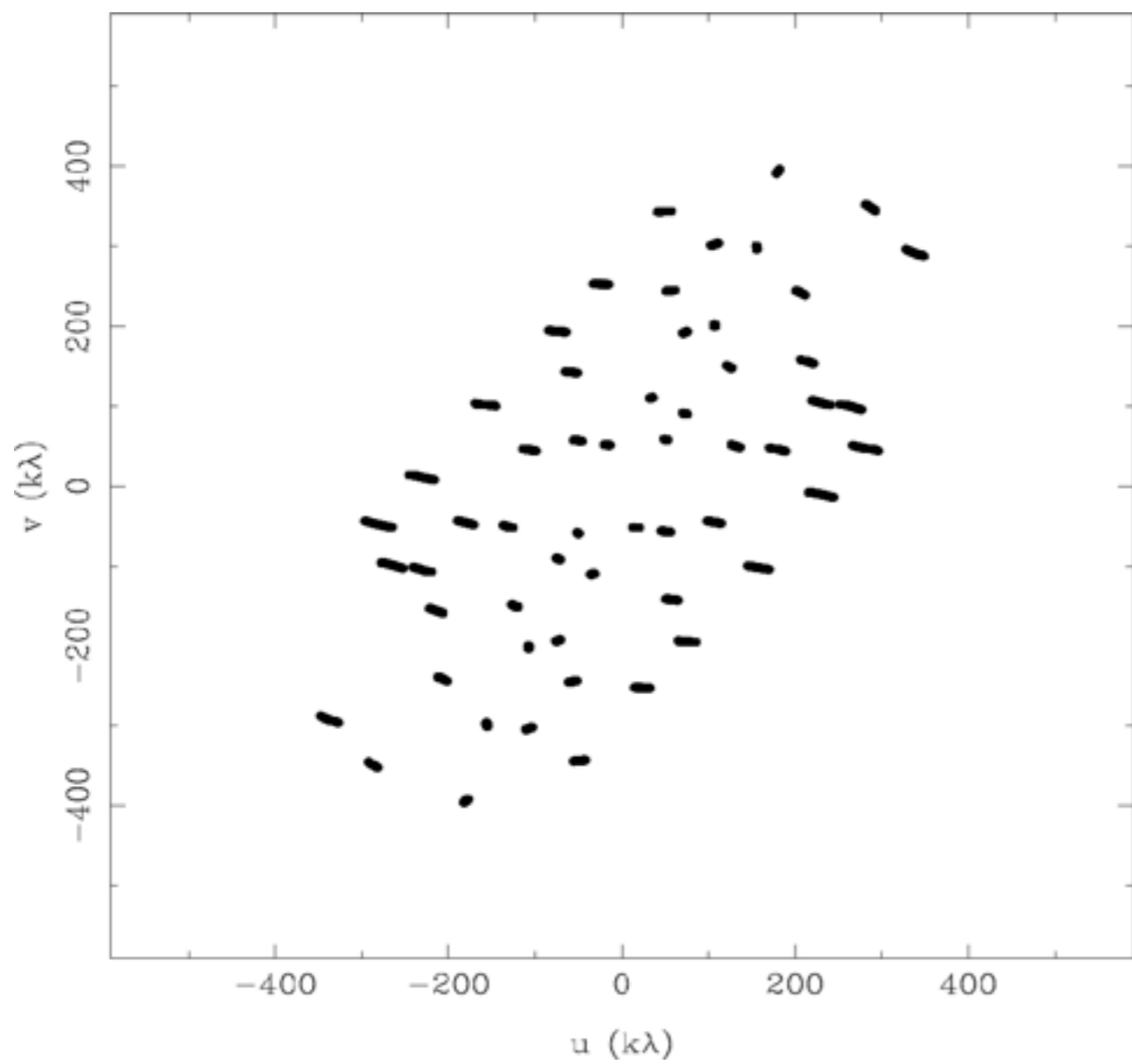
8 antennas x 6 samples



... or by increasing the integration time ...

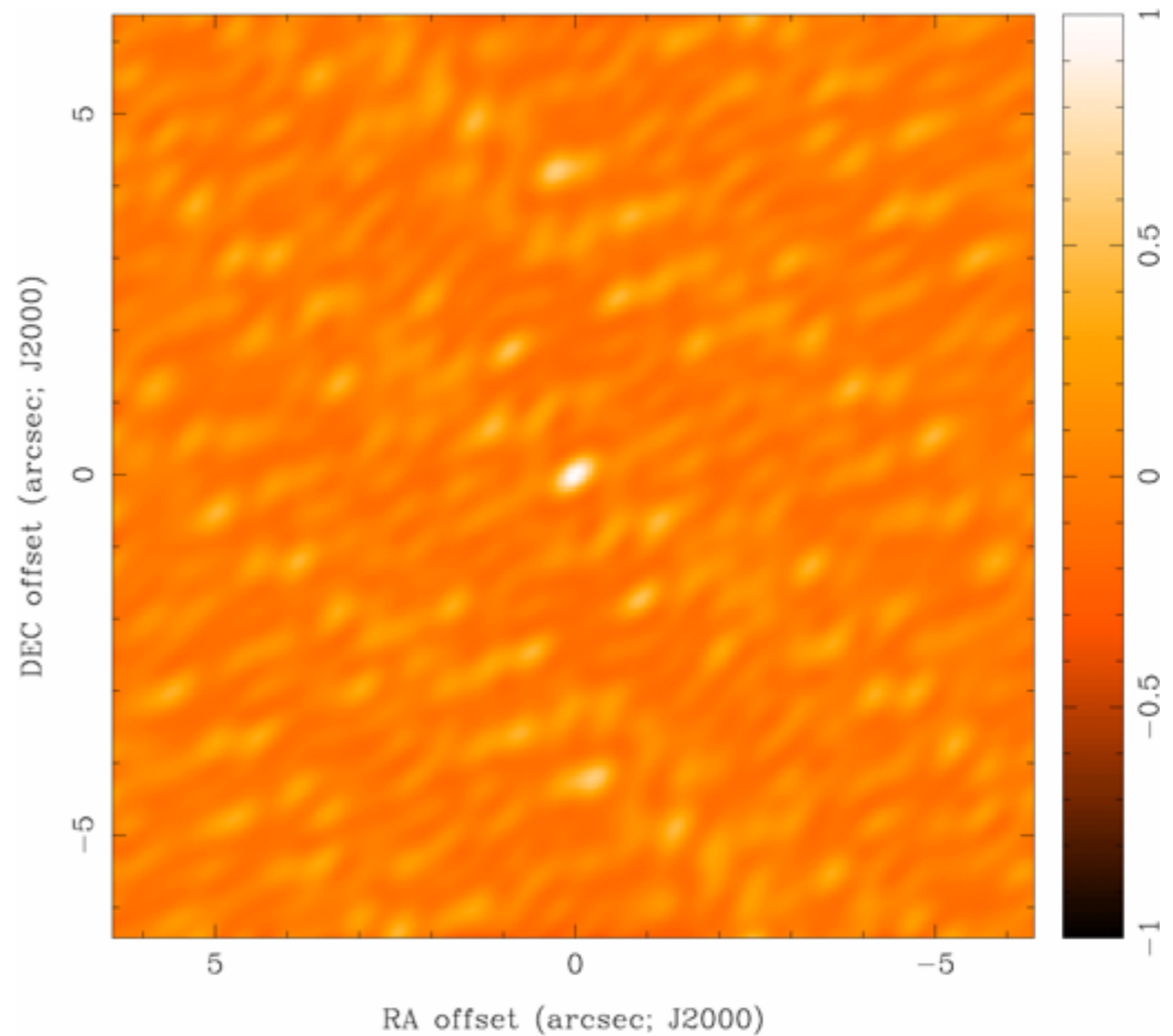
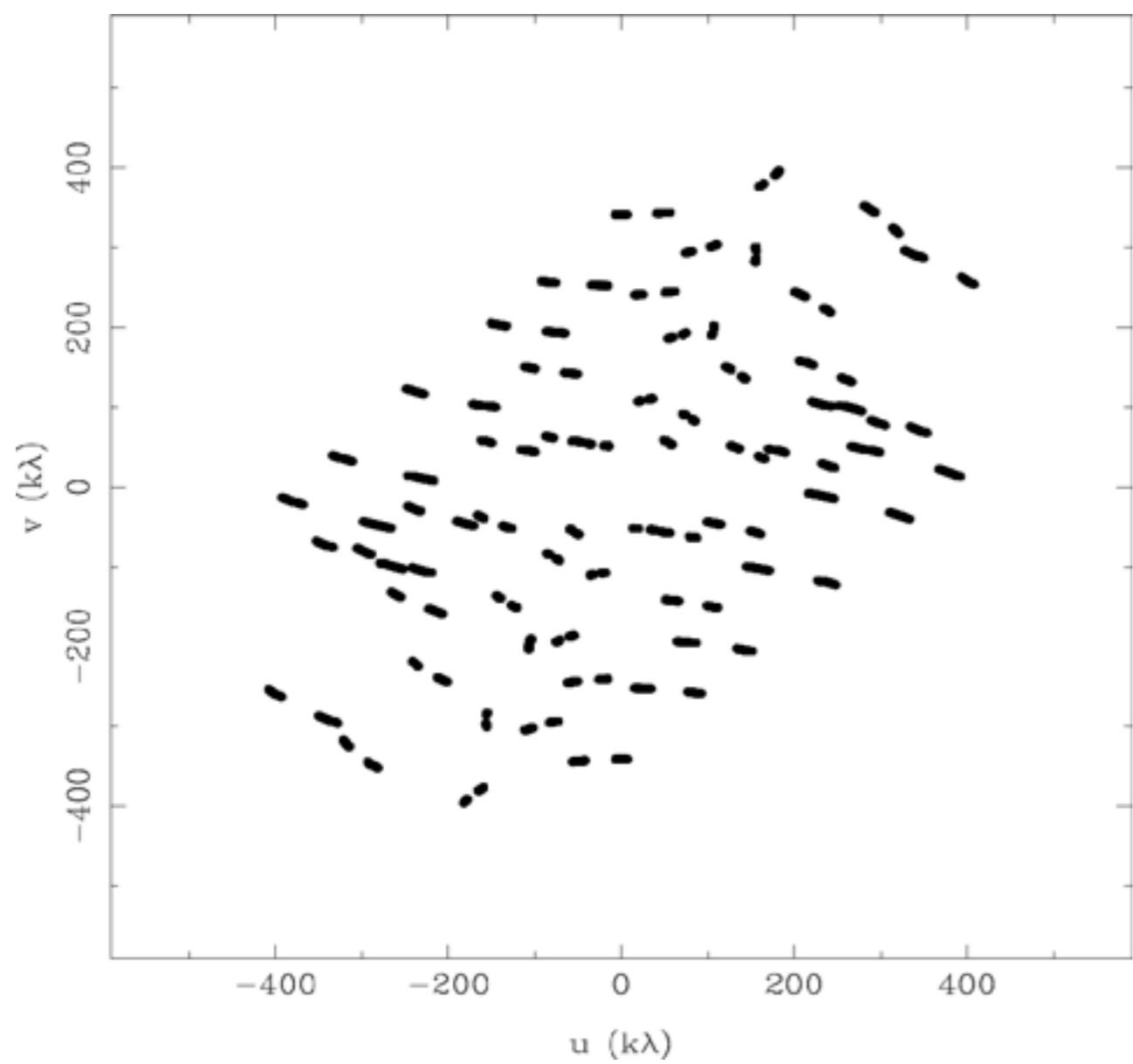
PSF shape vs. N ants

8 antennas x 30 samples



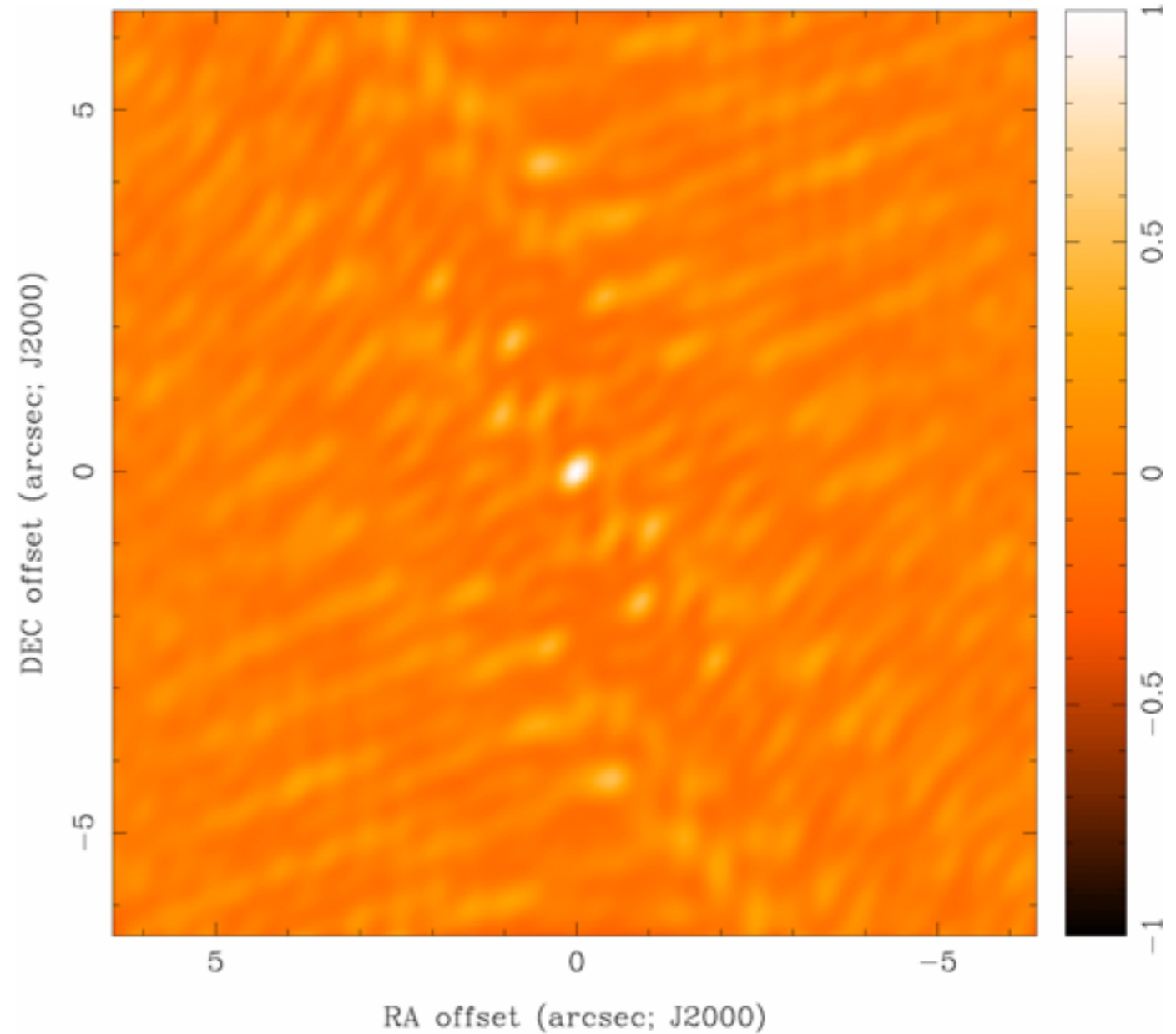
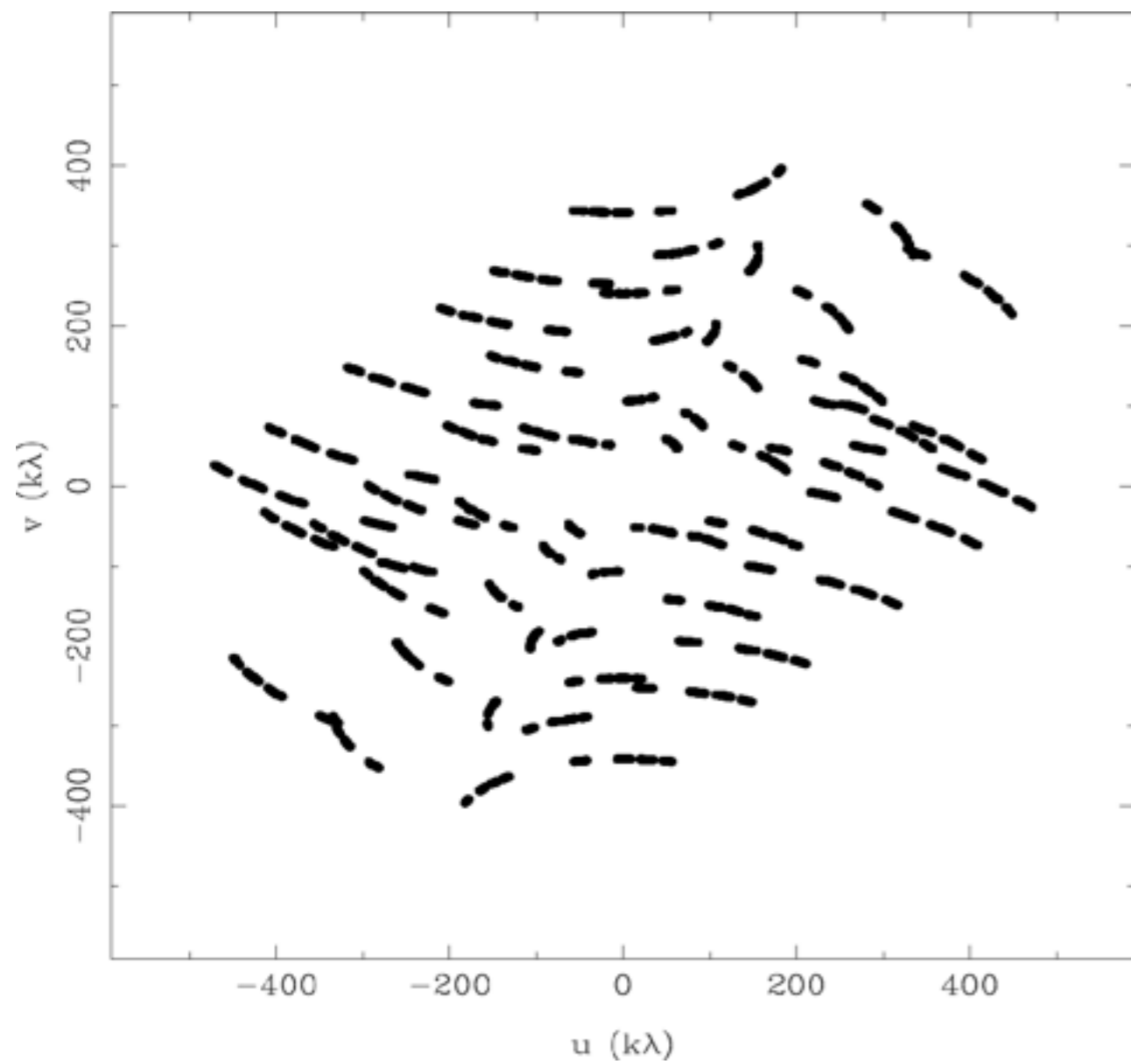
PSF shape vs. N ants

8 antennas x 60 samples



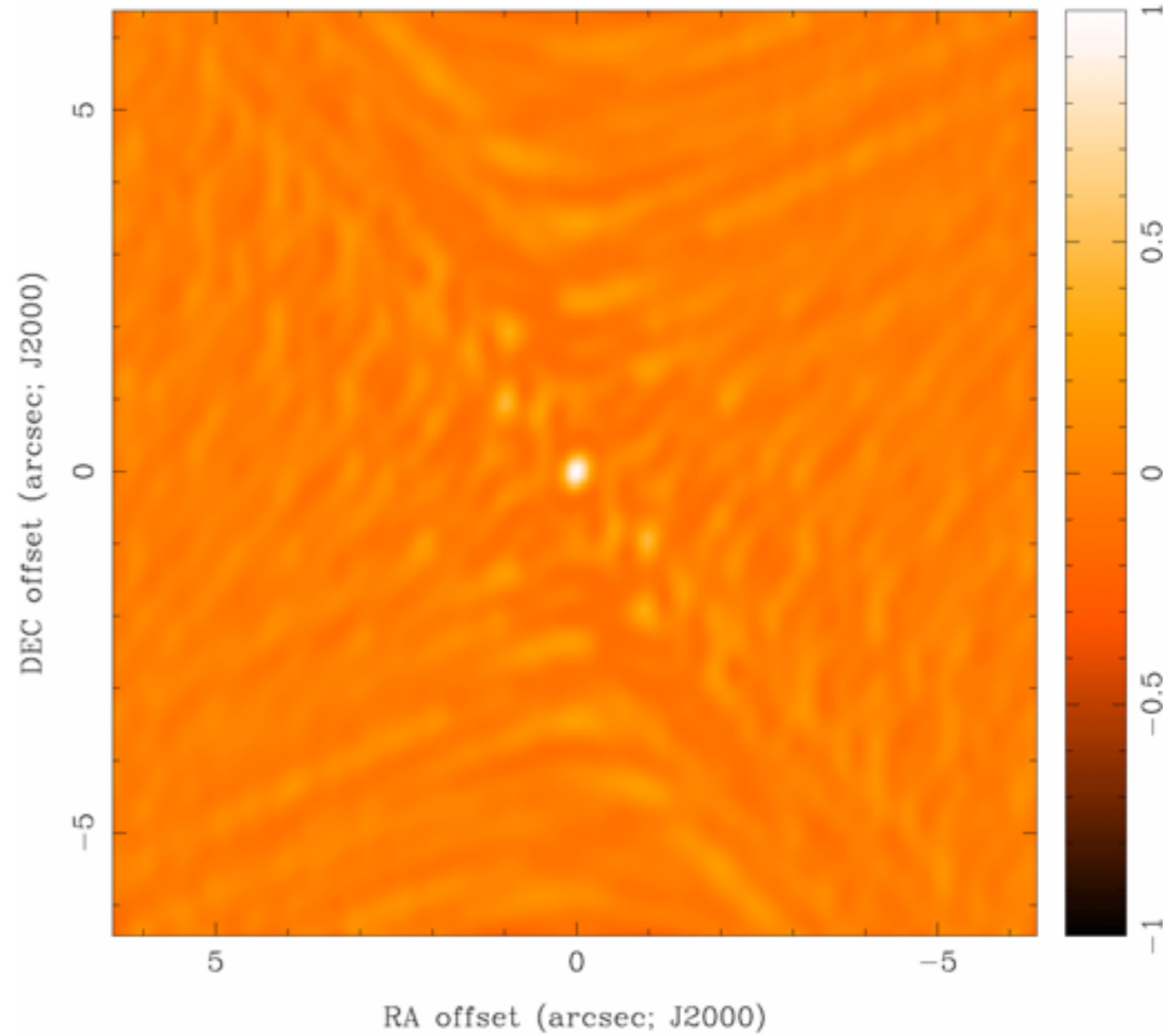
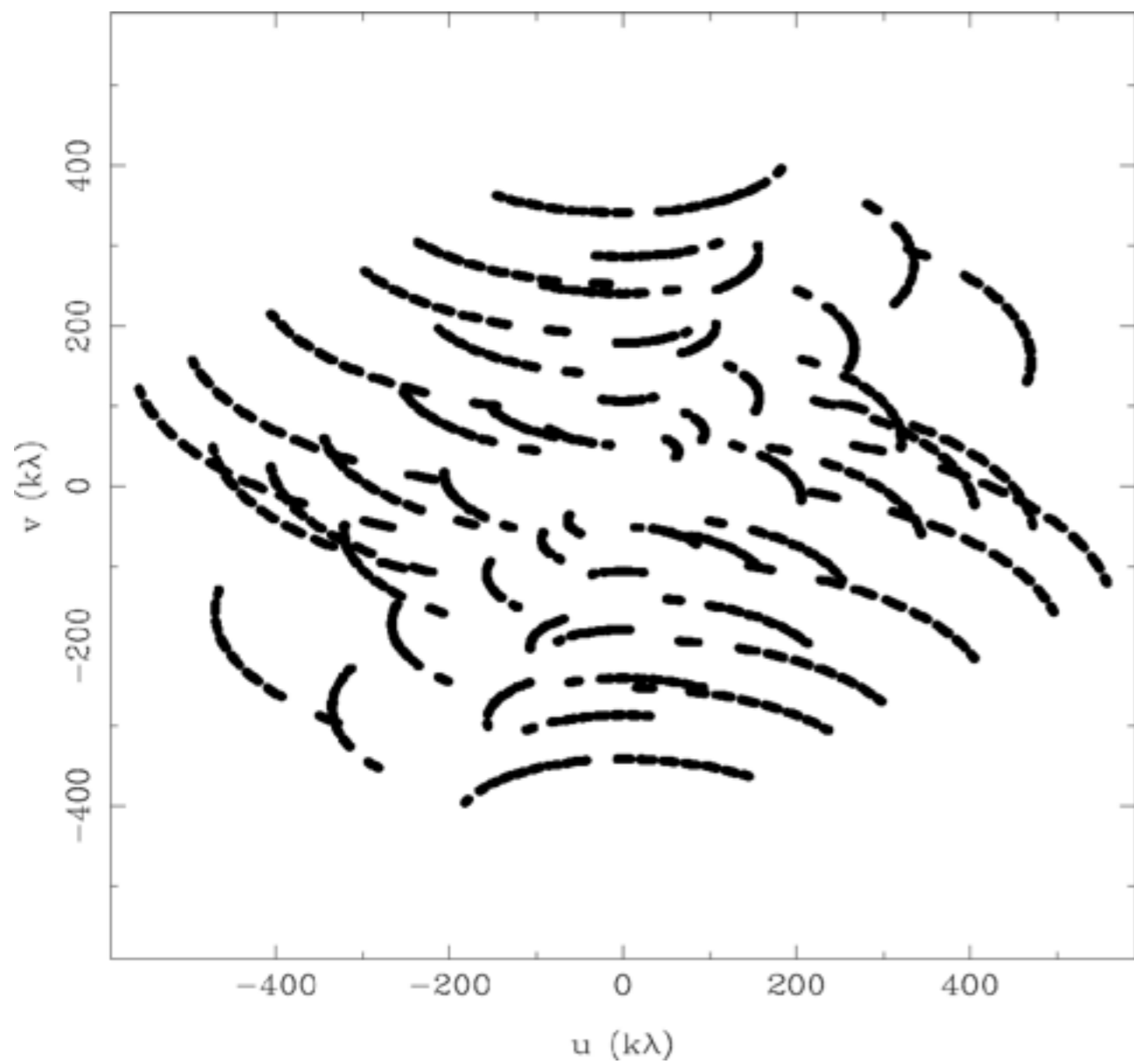
PSF shape vs. N ants

8 antennas x 120 samples



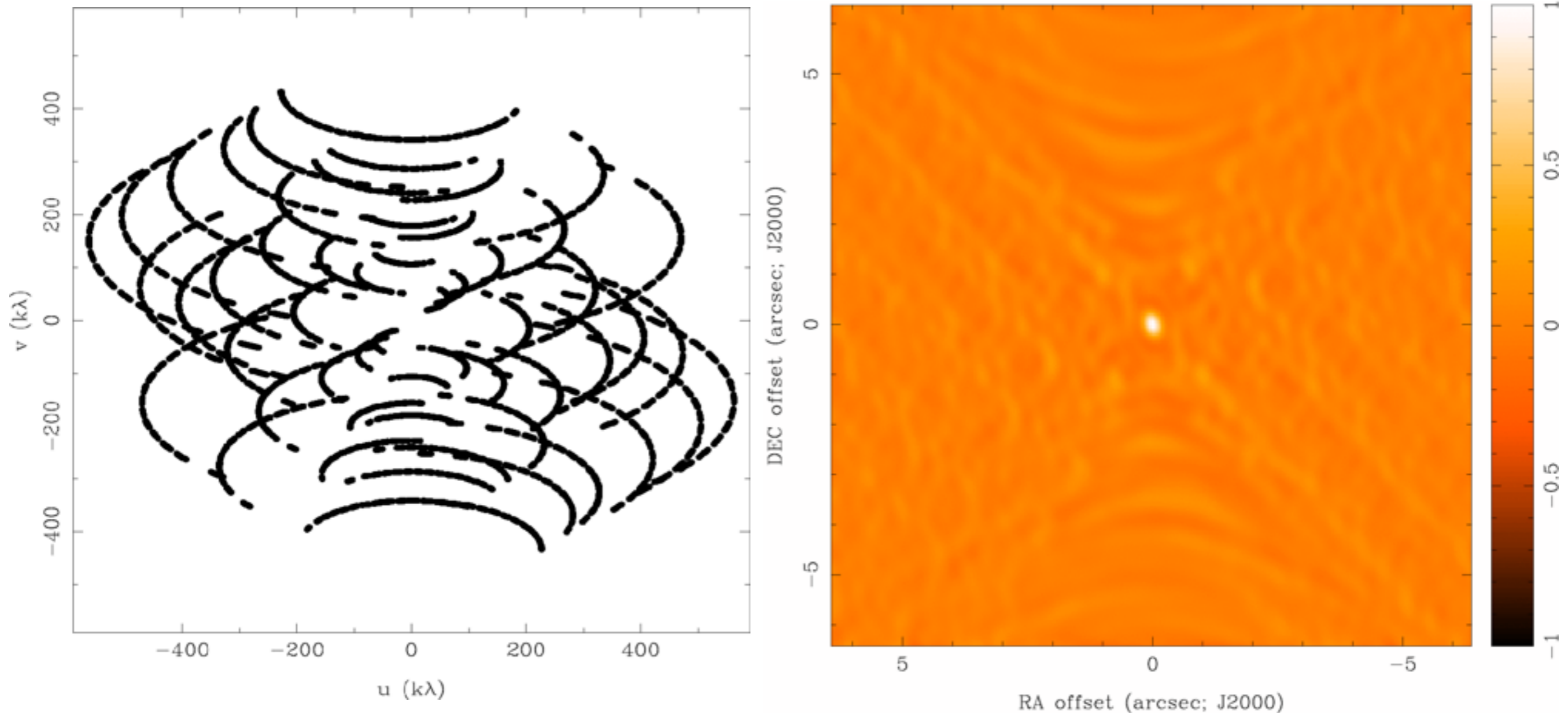
PSF shape vs. N ants

8 antennas x 240 samples



PSF shape vs. N ants

8 antennas x 240 samples



- ALMA has an “*instantaneous*” coverage uv plane...

Visibility and Sky Brightness

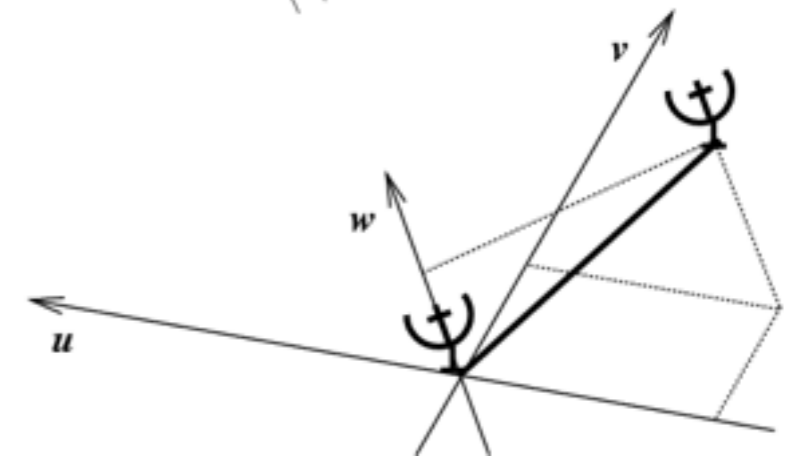
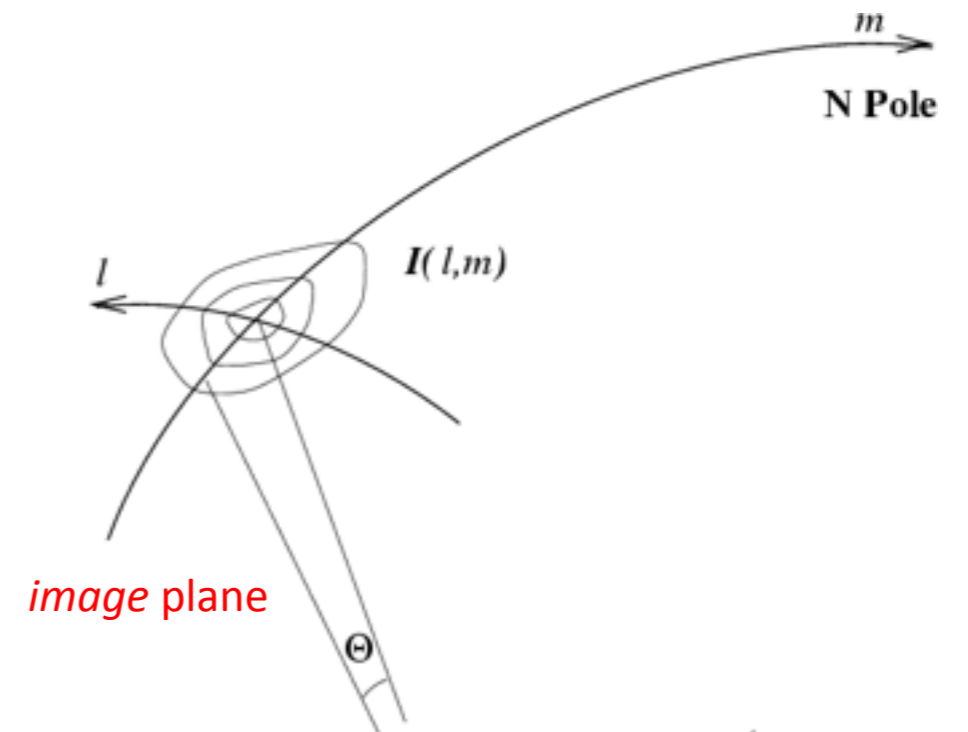
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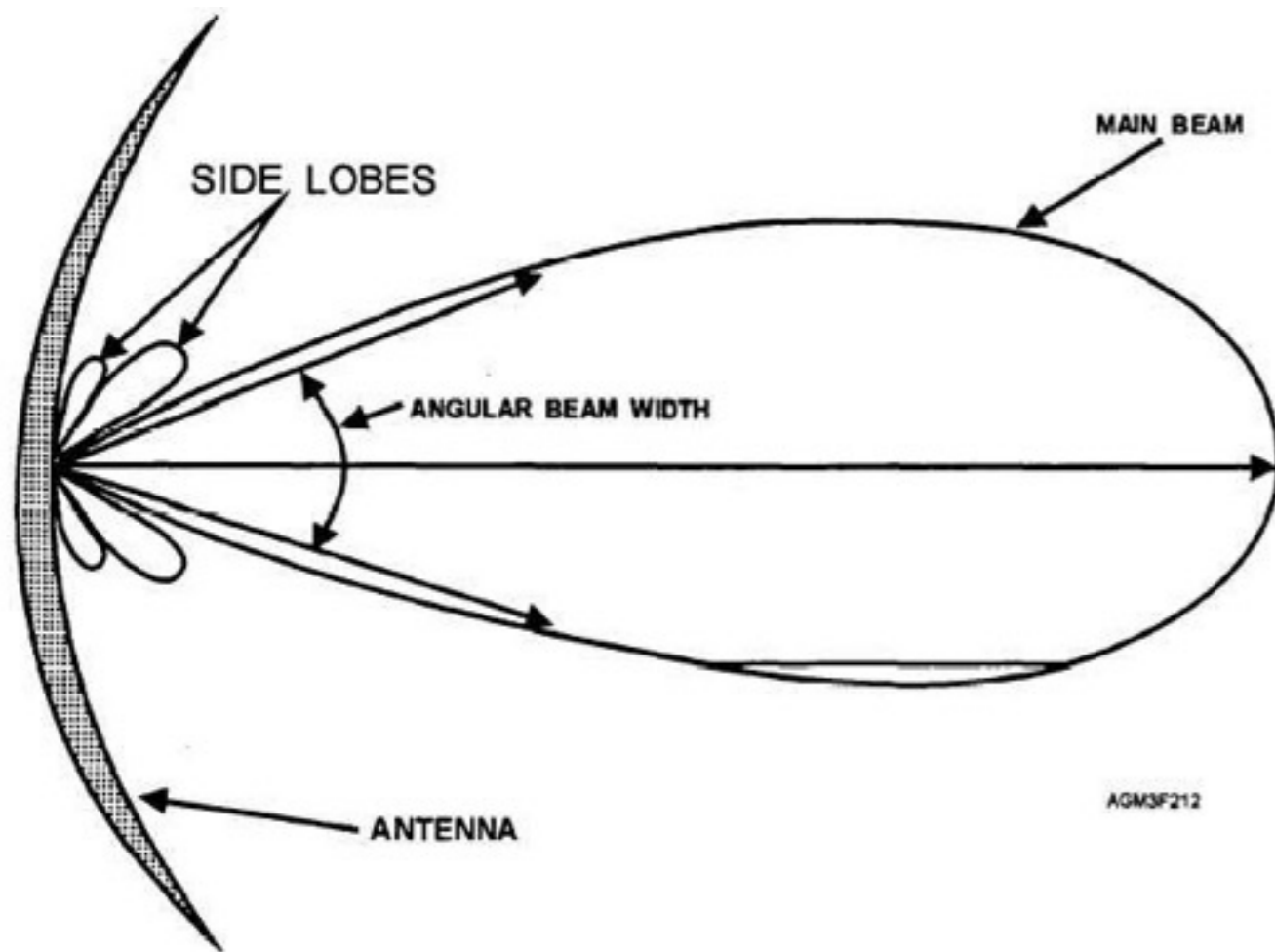
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uv plane

sampling uv vs FOV (o primary beam...)

- **Field of View**: depends on the single dish diameter



$$\mathcal{V}(u, v) = \iint A(l, m) I(l, m) e^{-2\pi i(ul+vm)} dl dm.$$

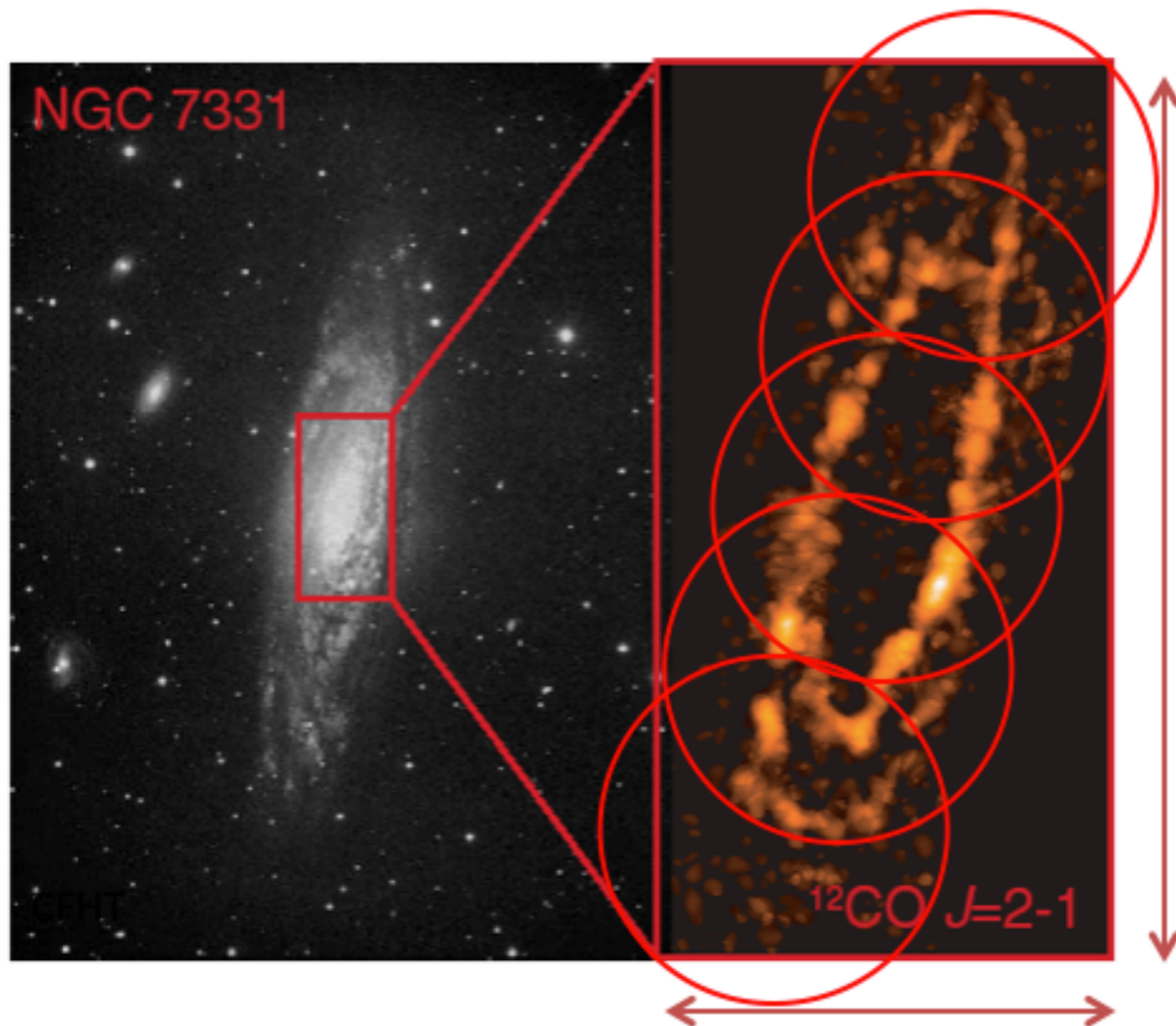
→ $FOV = 1.22\lambda/D$

smaller dish → larger FOV

→ if object "larger" than FOV ... mosaic!

sampling uv vs FOV (o primary beam...)

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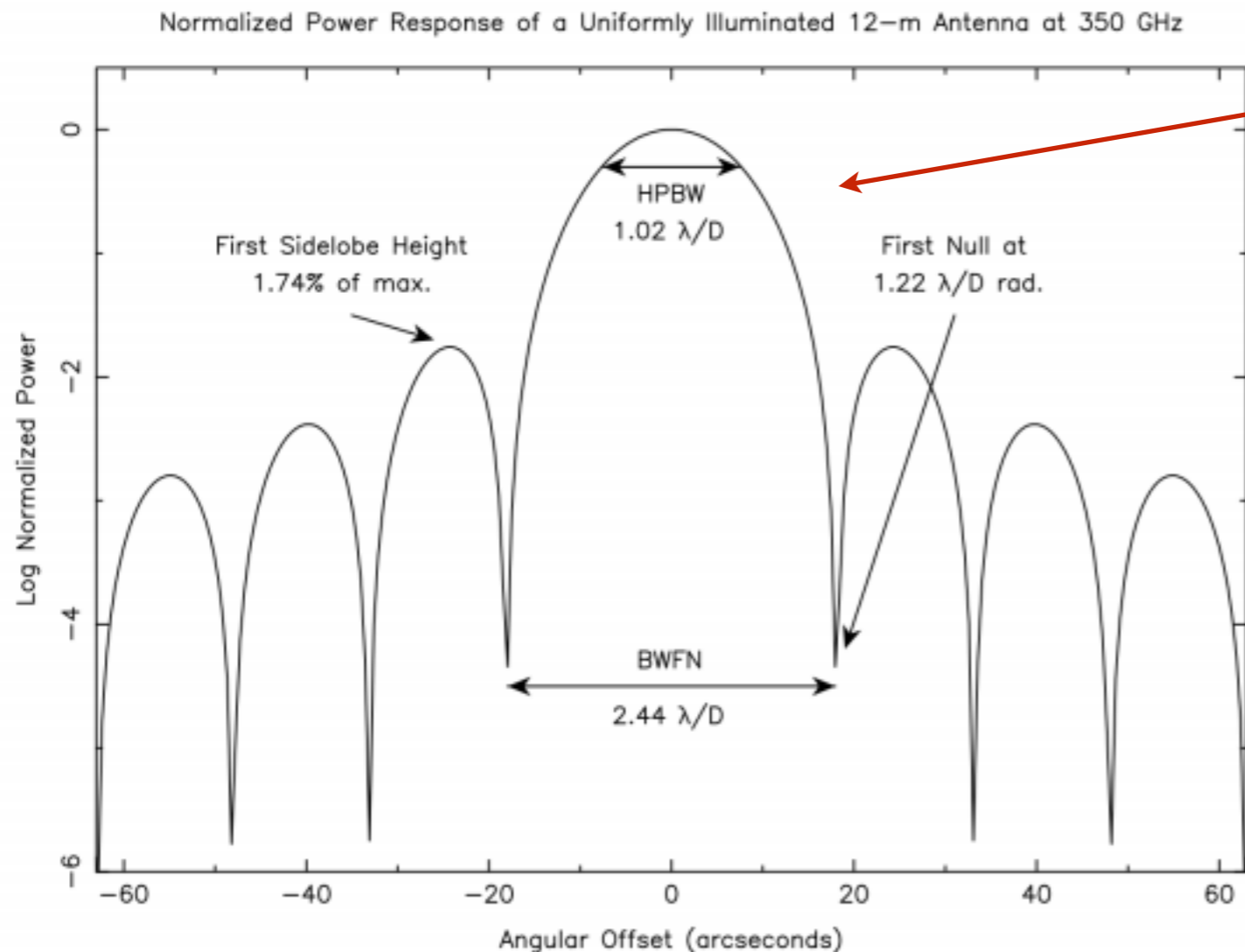
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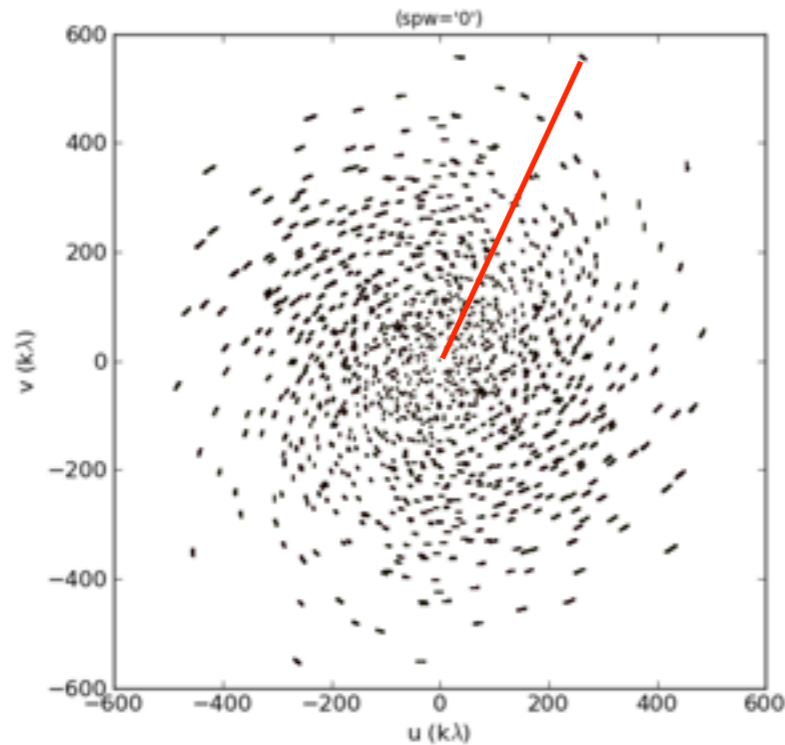
$$\text{FOV} = 1.22\lambda/D$$

smaller dish \rightarrow larger FOV

- \rightarrow decreasing sensitivity with the distance from image centre
- \rightarrow pbcorr images from archive (see Rosita's talk)
- when you deal with mosaic images, uniform noise over an area larger than 1/3 PB

sampling uv vs PSF (o synth beam...)

- **Angular resolution/Synthetized Beam:**
 - Synth beam = the way the interferometer “sees” a point source
 - angular resolution= FWHM synthetized beam
 - depends on maximum distance between antennas



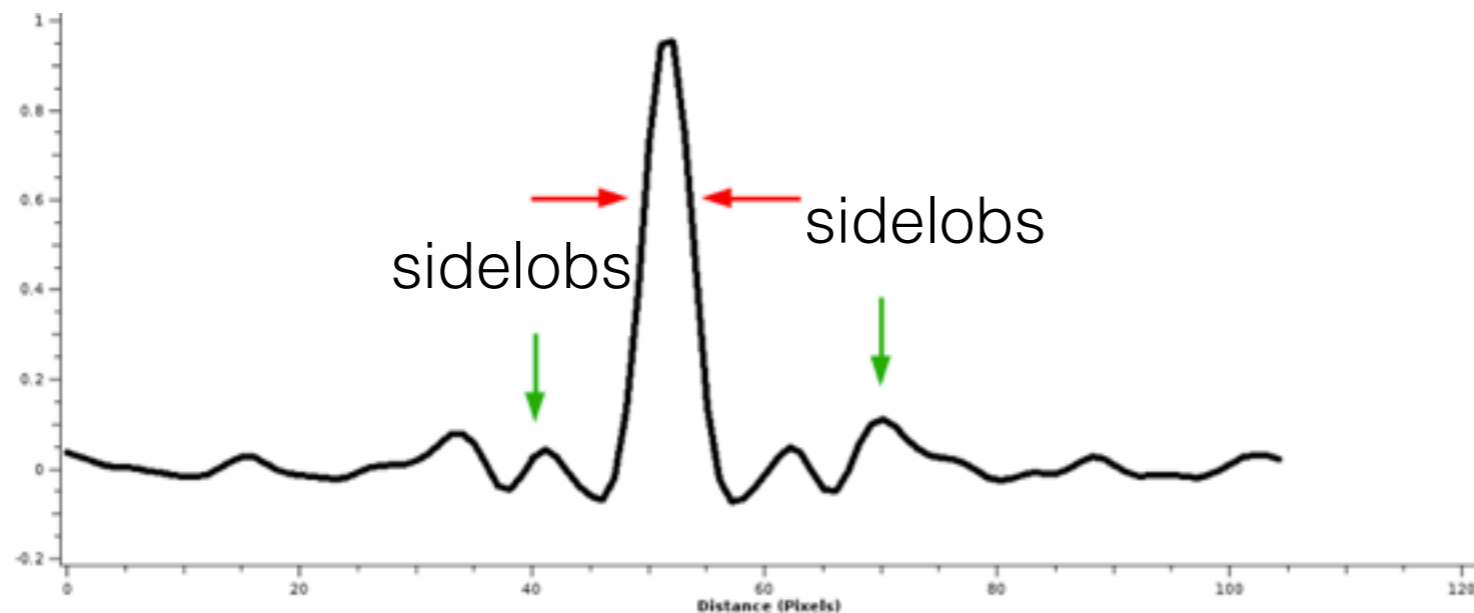
$$\theta_{\max} = k\lambda / D_{\max}$$

$k \sim 1$ ”, weighting of visibilities

$$\mathcal{V}(u, v) = \iint \mathcal{A}(l, m) I(l, m) e^{-2\pi i(ul + vm)} dl dm.$$

- more distant \rightarrow more resolution (image details)
 - ok for compact objects ... (increase of brightness)
 - careful with extended objects

sampling uv vs PSF (o synth beam...)



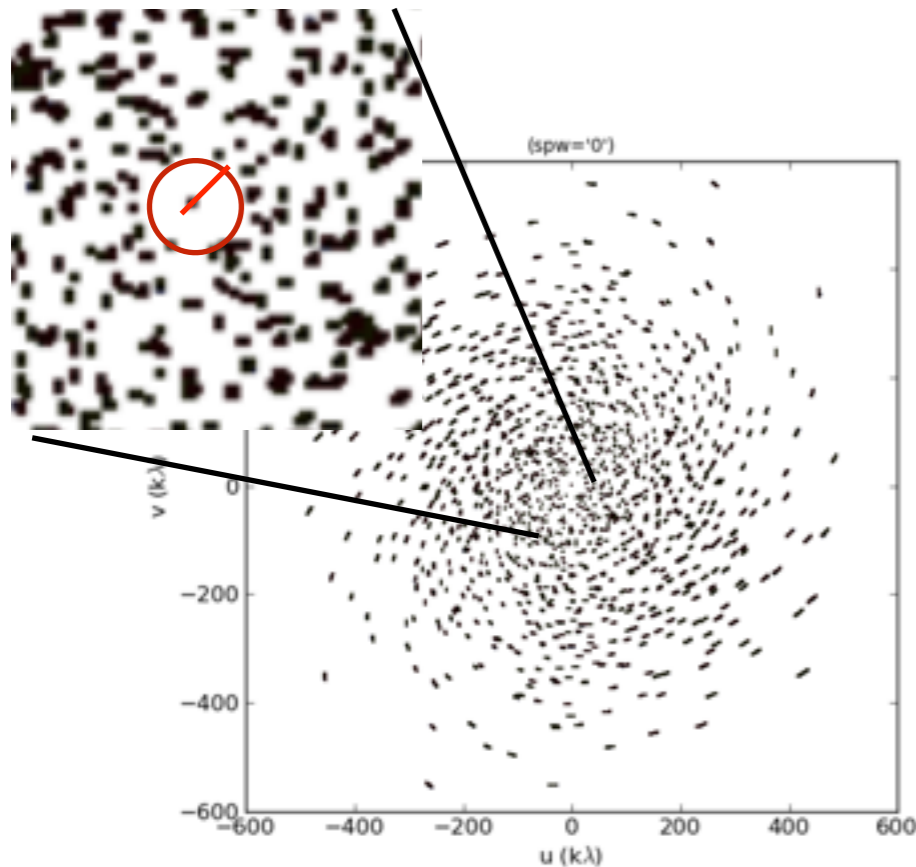
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sampling uv vs. MRS

- **Maximum recoverable scale**: depends on minimum distance between antennas

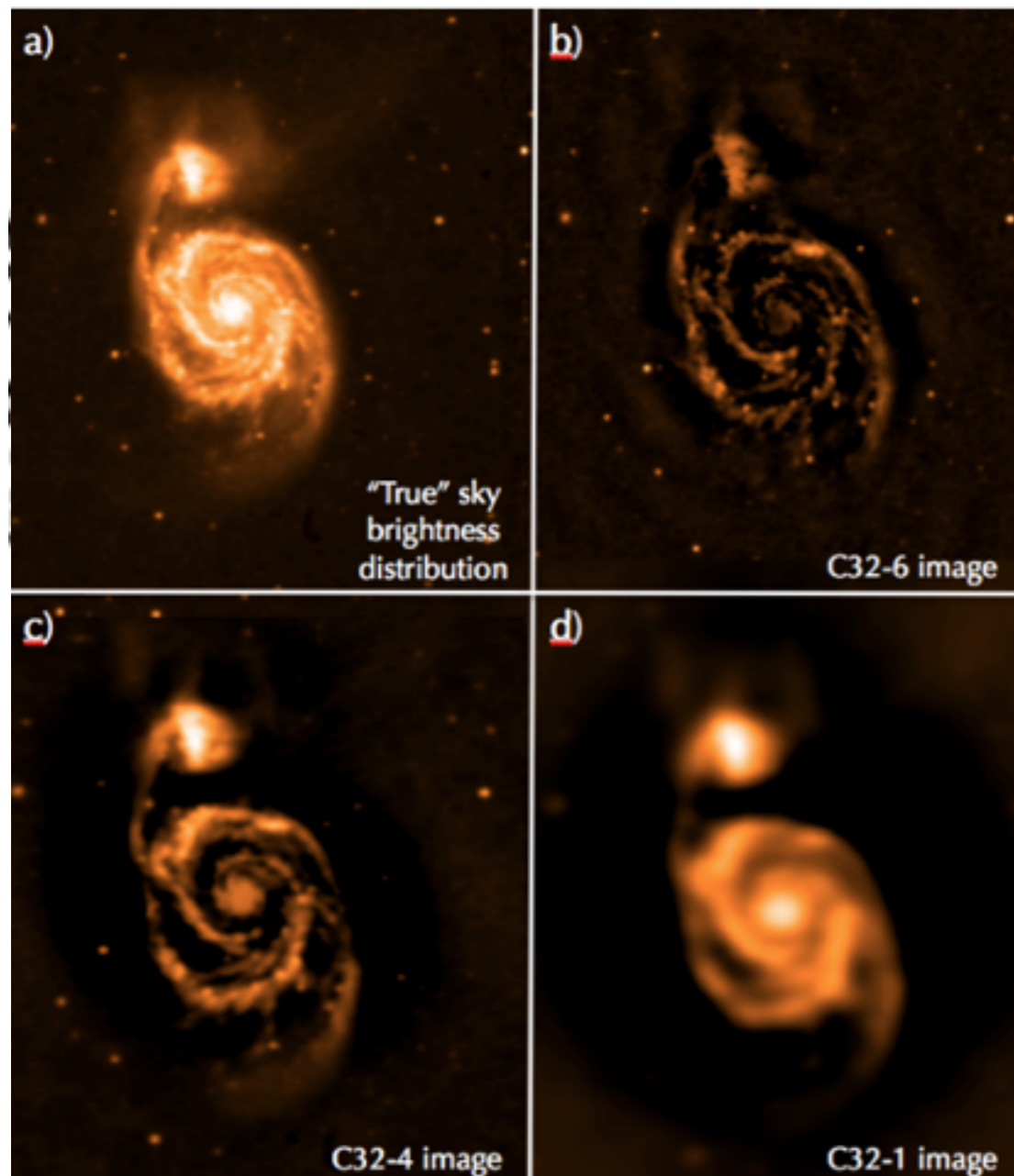


$$\theta_{MRS} \approx \frac{0.6 \lambda}{L_{min}} [\text{radians}] \approx \frac{37100}{L_{min} \nu} [\text{arcseconds}]$$

- more compact → sensitive to extended sources

sampling uv vs. MRS

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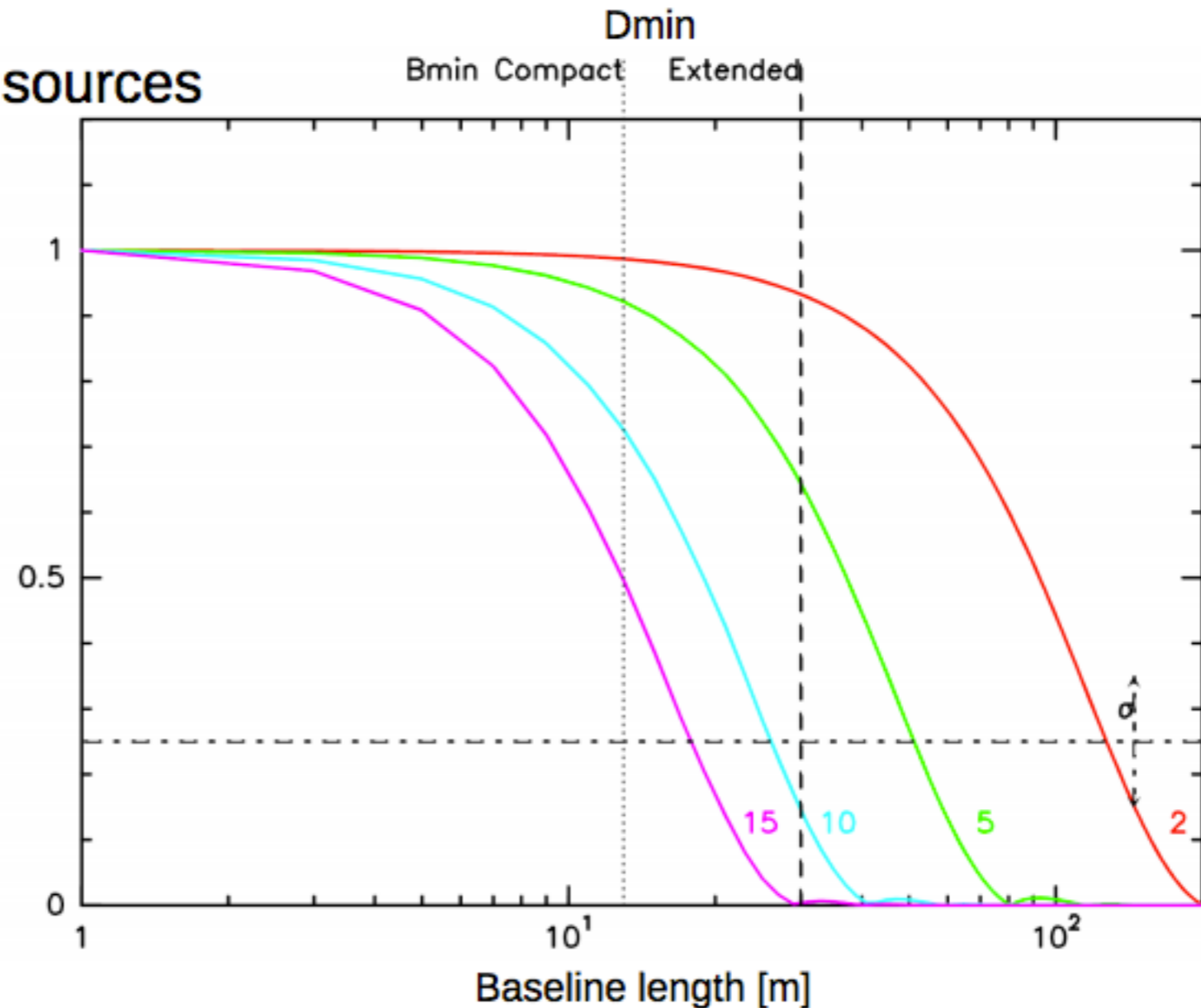
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sampling uv vs. MRS the zero spacing problem

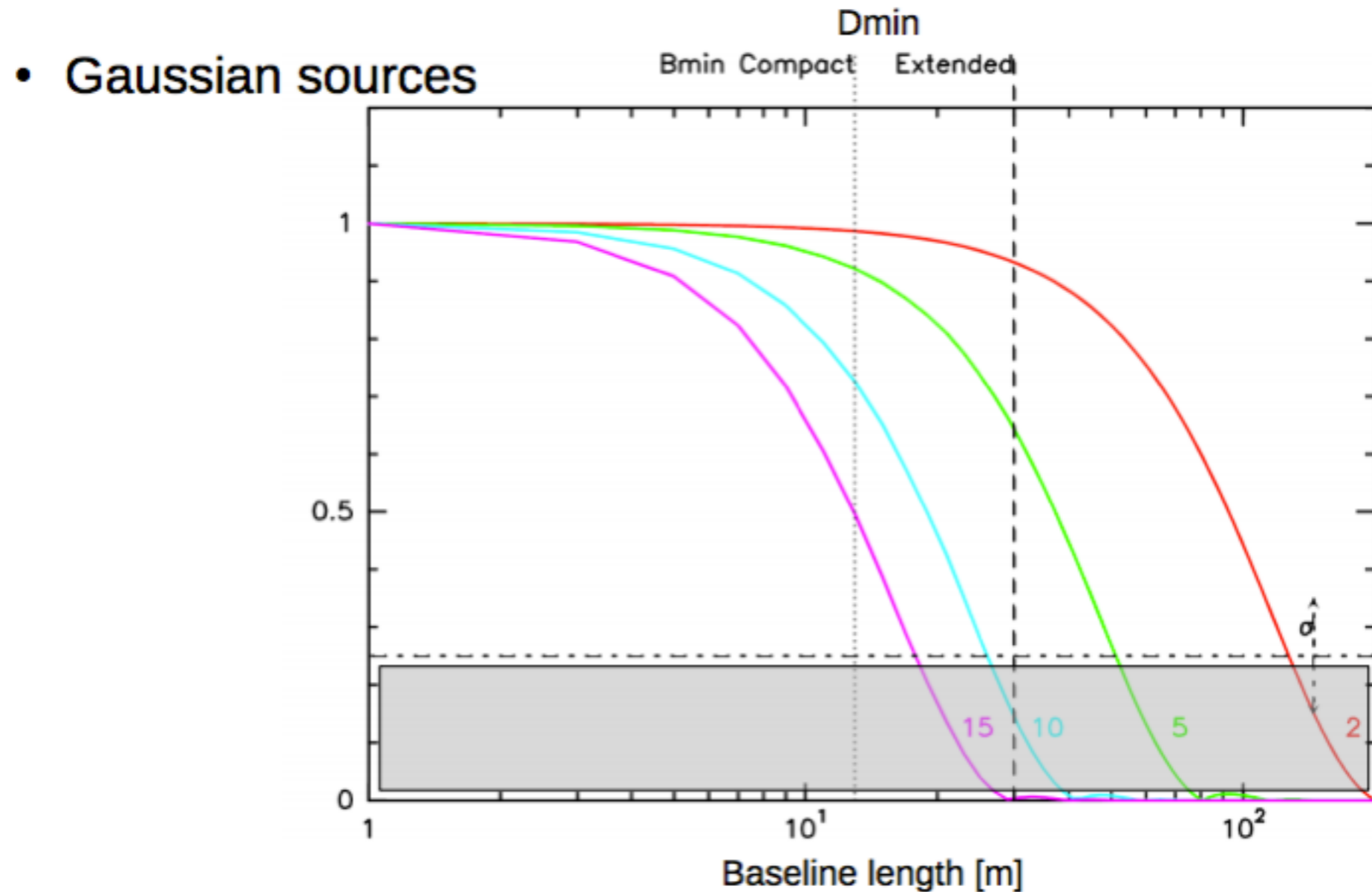
- Zero/ short spacing missing in interferometry
 - filtering of large scale emission

- Gaussian sources



sampling uv vs. MRS the zero spacing problem

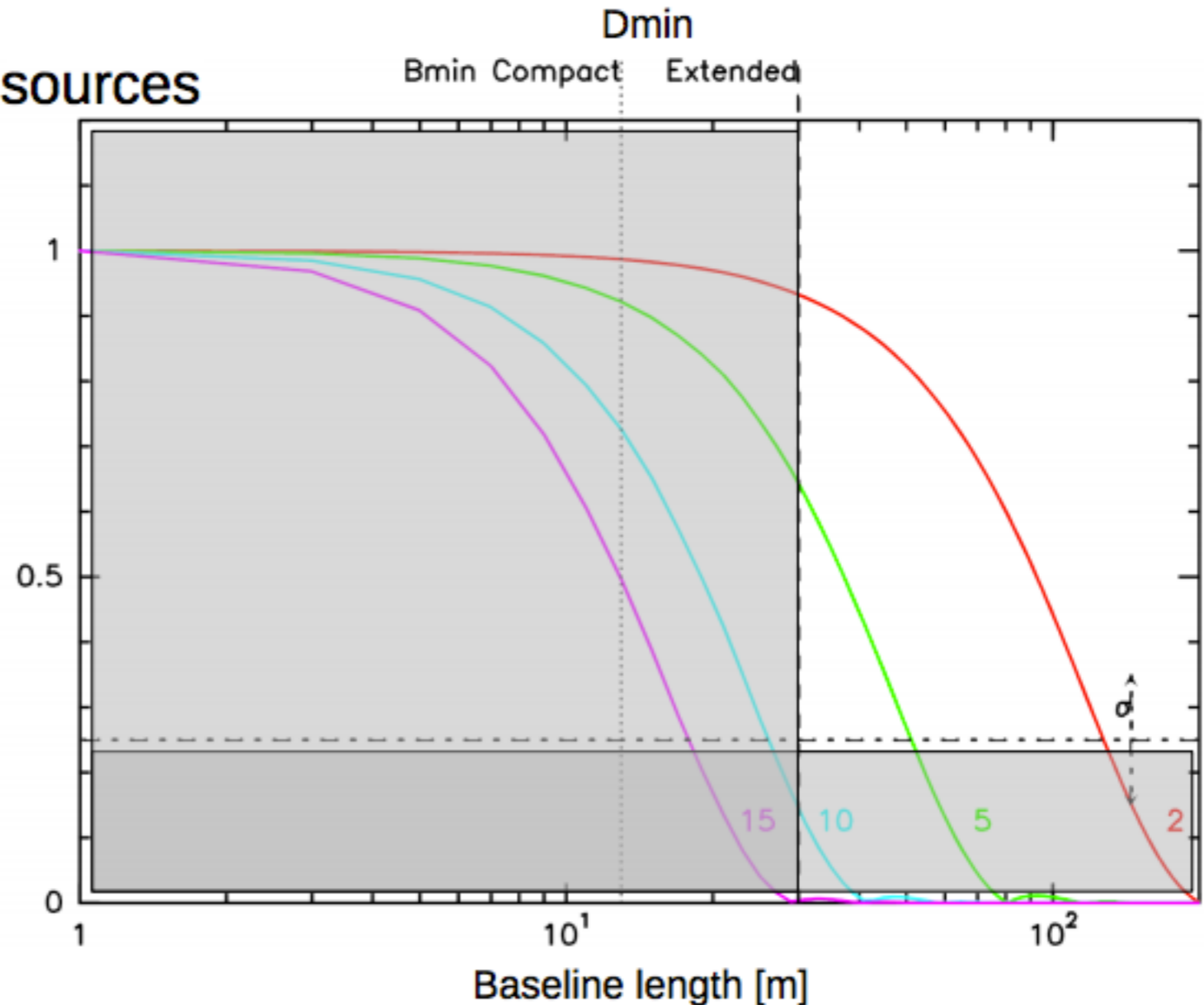
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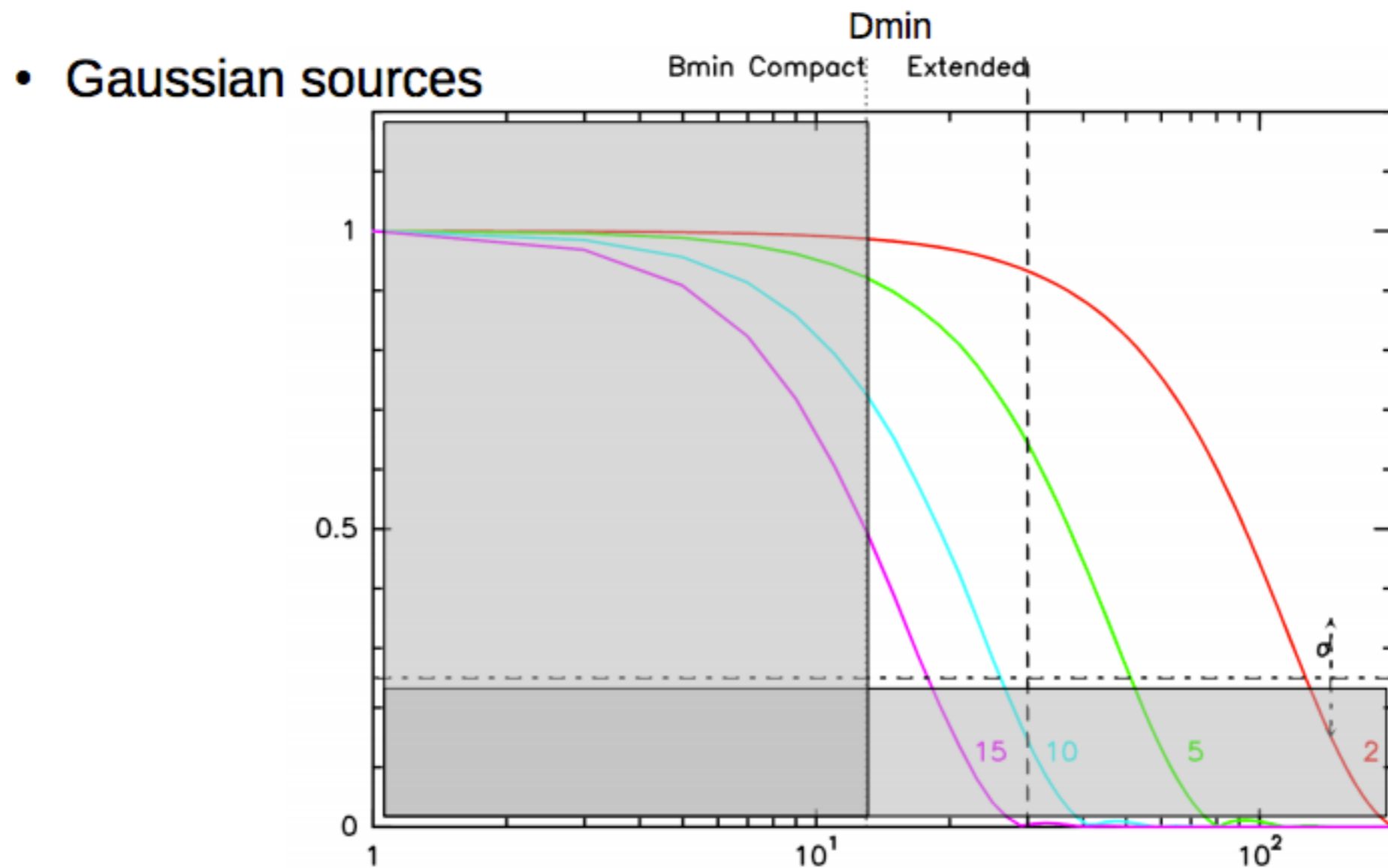
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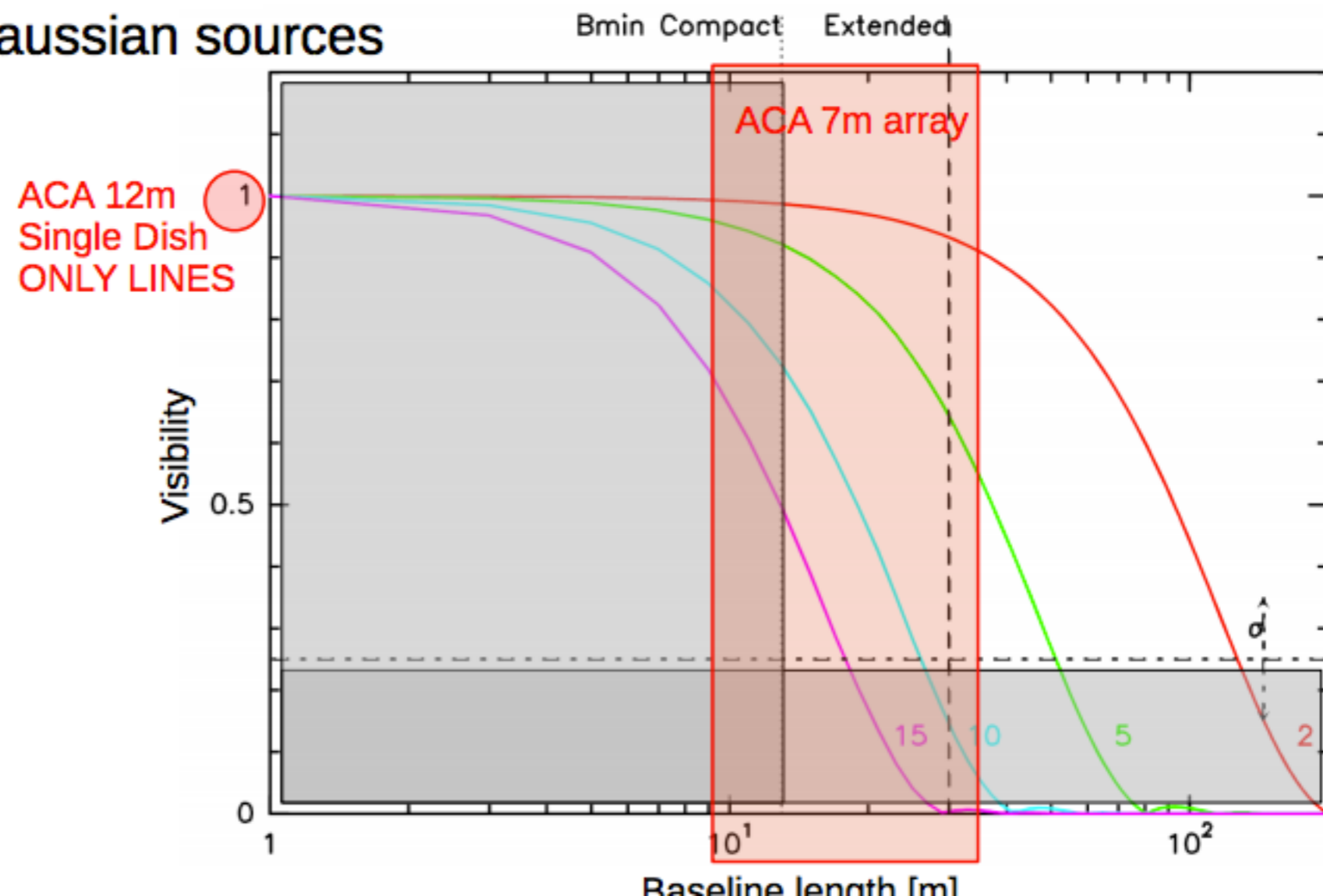
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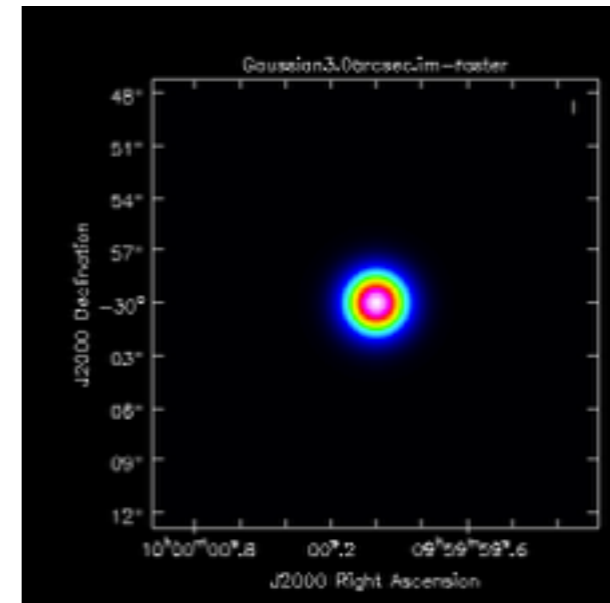
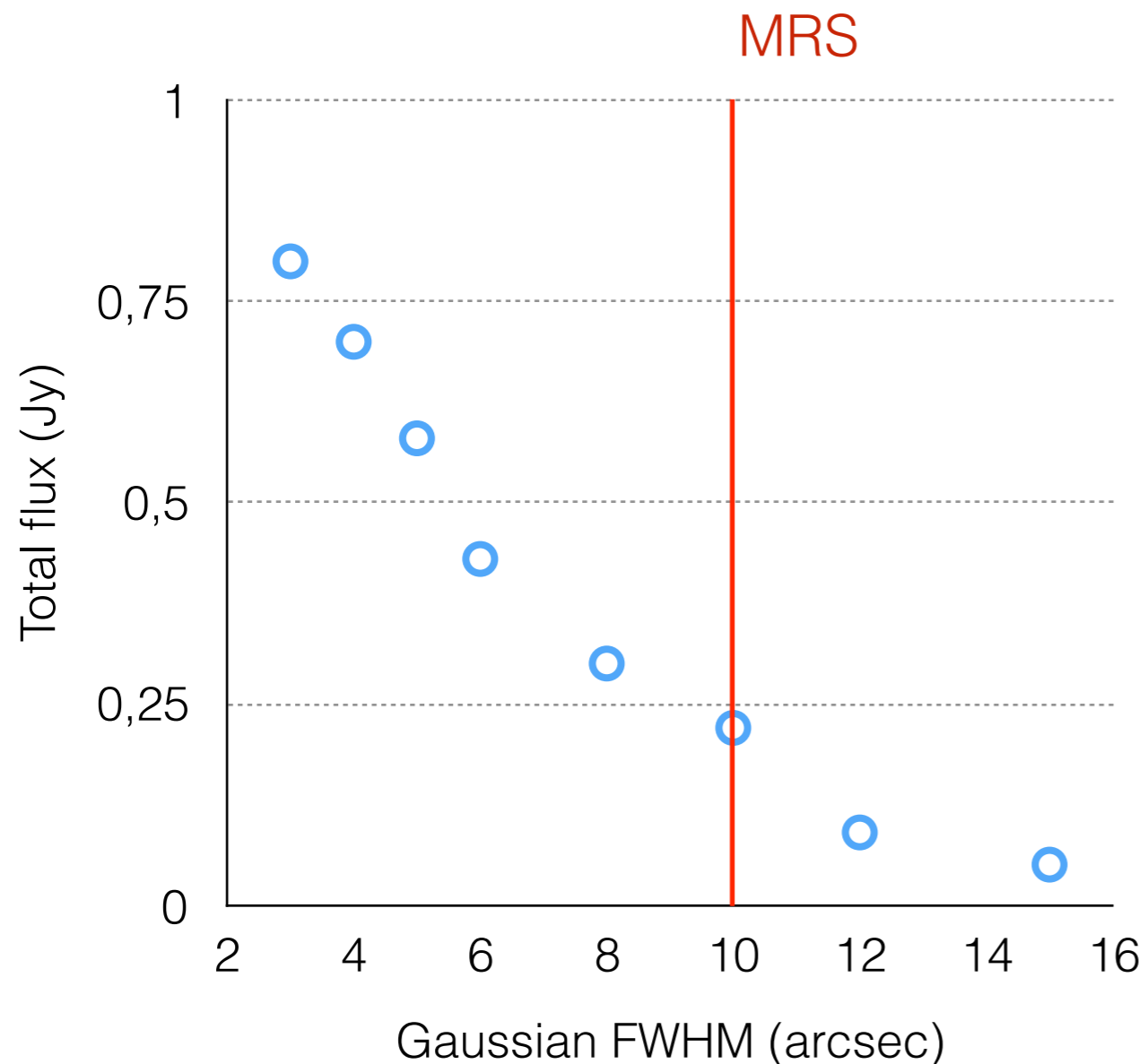
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- Gaussian sources



sampling uv vs. MRS the zero spacing problem

- how the interferometer “sees” different FWHM Gaussian Sources (Total Flux = 1Jy)
 - MRS ~ 10 arcsec



lost a lot of flux!!

—> ACA

—> TP

Glossary: Flux vs. Brightness

- Temperature and Fluxes (Rayleigh-Jeans)

- S = Flux density (Jy, Jy per beam)
- T = brightness temperature (K)
- k Boltzmann constant
- Ω_S solid angle (steradian)
- θ_b HPBW of a gaussian

$$I_\nu(\theta, \varphi) = \frac{2k\nu^2}{c^2} T_B(\theta, \varphi).$$

$$S_\nu = \frac{2k\nu^2}{c^2} \int T_B d\Omega.$$

$$\left(\frac{T}{1 \text{ K}} \right) = \left(\frac{S_\nu}{1 \text{ Jy}} \right) \left[13.6 \left(\frac{300 \text{ GHz}}{\nu} \right)^2 \left(\frac{1''}{\theta_{max}} \right) \left(\frac{1''}{\theta_{min}} \right) \right].$$

$$1 \text{ Jy} = 10^{-26} \text{ W m}^{-2} \text{ Hz}^{-1} = 10^{-23} \text{ erg s}^{-1} \text{ cm}^{-2} \text{ Hz}^{-1}$$

Glossary: Flux vs. Brightness

- **Sensitivity**: depends on ... a lot of things

The rms noise in the signal (sensitivity):

T_{sys} is the brightness temperature equivalent to the flux received from the antenna **source**, atmosphere, instrumental noise....

$$\sigma_S = \frac{2kT_{\text{sys}}}{\eta_q \eta_c A_{\text{eff}} \sqrt{N(N-1)} n_p \Delta\nu t_{\text{int}}}$$

Sensitivity can be improved by:

- getting **lower T_{sys}** (sites with low water vapour levels)
- increasing the **collecting area**
- increasing the **bandwidth** and/or the **integration time**

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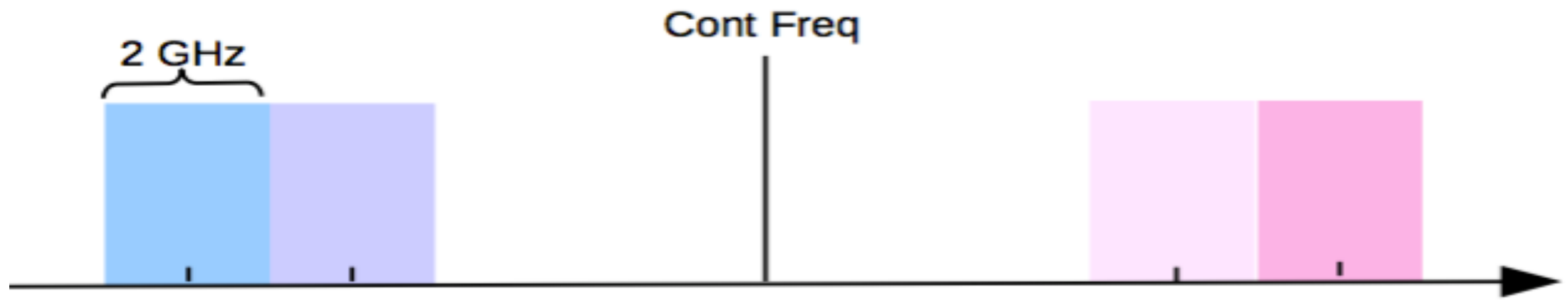
helpful for ARCHIVE data?

YES! You can average channels for lower rms

The interferometric data output

(ALMA) data format—> the cube

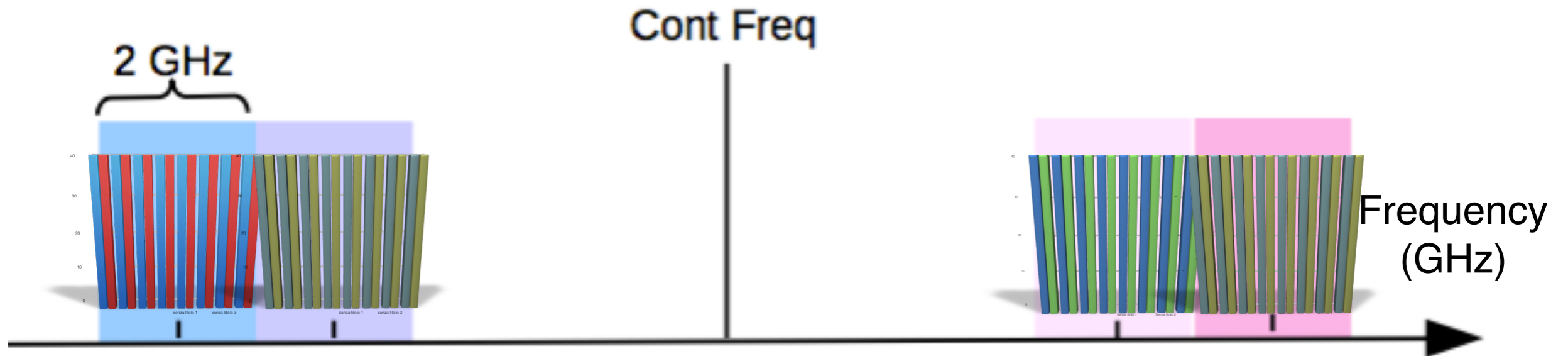
@mm wavelengths molecular spectroscopy
wide spectral range (~8GHz)
each spw divided into several channels



The interferometric data output

(ALMA) data format—> the cube

@mm wavelengths molecular spectroscopy
wide spectral range (~8GHz)
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The interferometric data output

(ALMA) data format—> the cube

From each channel, one uv-plane/image is produced

Spectral line observations have up to 3840 channels. The highest spectral resolution achievable is 30 kHz.

