

A closer look at CASA

Dirk Petry (ESO), April 2010

Outline

→ **application overview** - the CASA system of applications

→ tasks and tools - the two-level user interface revisited

→ **global variables** - Python global variables and the task parameters

→ **non-interactive casapy** - casapy command line options

→ Measurement Set, ASDM, uvfits - the visibility data formats

→ calibration tables
 - CASA tables for calibration data

→ **CASA** images and FITS - image storage in tables and FITS files

→ **if you encounter problems** - how and where to file a helpdesk ticket



CASA application overview

In release 3.0.1: 8 independent applications exposed to the user:

casapy	 the CASA "shell"
casapyinfo	 returns info about how CASA was built
casabrowser	 == browsetable() task within casapy
casalogger	 the logger started by default with casapy
casaplotms	 will be == plotms() task within casapy
casaviewer	 == viewer() task within casapy
asdm2MS	 the ASDM to MS converter, importasdm in casapy
buildmytasks	 integrates user-provided tasks into casapy (see appendix H of the cookbook)



Two level user interface: Top level == Tasks (91 in release 3.0.1, see taskhelp)

	•	•		, , ,
accum	feather	importevla	plotants	sdscale
applycal	find	importfits	plotcal	sdsim
autoclean	fixvis	importgmrt	plotms	sdsmooth
bandpass	flagautocorr	importoldasdm	plotxy	sdstat
blcal	flagdata	importuvfits	polcal	sdtpimaging
boxit	flagmanager	importvla	rmtables	setjy
browsetable	fluxscale	imregrid	sdaverage	simdata
calstat	fringecal	imsmooth	sdbaseline	smoothcal
clean	ft	imstat	sdcal	specfit
clearcal	gaincal	imval	sdcoadd	split
clearplot	gencal	listcal	sdfit	uvcontsub
clearstat	hanningsmooth	listhistory	sdflag	uvcontsub2
concat	imcontsub	listobs	sdimaging	uvmodelfit
cvel	imfit	listvis	sdimprocess	uvsub
deconvolve	imhead	makemask	sdlist	viewer
exportasdm	immath	mosaic	sdmath	viewerconnection
exportfits	immoments	newflagdata	sdplot	vishead
${\tt exportuvfits}$	importasdm	peel	sdsave	visstat
				widefield



Two level user interface: Top level == *Tasks*

documented in

a) built-in documentation

```
help <taskname>
pdoc <taskname>
<taskname> ?
```

- b) task reference web page http://casa.nrao.edu/docs/taskref/TaskRef.html
- c) cookbook http://casa.nrao.edu/Doc/Cookbook/casa_cookbook.pdf

Note: there is also the CASAGuides wiki http://casaguides.nrao.edu/



Two level user interface: Top level == *Tasks*

- provide all basic analysis functionality for inexperienced users (without Python knowledge)
- provide the common analysis functionality for experienced users
- user interface optimised for interactive work with additional helper commands

command example

default default(clean) - reset all input parameters

inp inp - show parameters of current task

go go - start current task

saveinputs saveinputs(clean, parfile) - store parameters in file

tget tget(clean, parfile) - restore parameters from file



Two level user interface: bottom level == Tools (17 of them for release 3.0)

```
cb (calibrater) cp (cal plot) fg (flagger)
ia (image analysis) im (imager) me (measures)
mp (MS plot) ms (MS) qa (quanta)
sm (simulation) tb (table) tp (table plot)
vp (voltage patterns) cs (coord. sys.) at (atmosphere)

pl (pylab functions)
sd (ASAP functions - run asap_init() to import into CASA)
```



Two level user interface: bottom level == *Tools*

documented in

a) built-in documentation

help <toolname>
help <toolname>.<methodname>

b) toolkit manual web page

http://casa.nrao.edu/docs/casaref/CasaRef.html



Two level user interface: bottom level == *Tools*

- contain all the special CASA functionality as Python objects
- not optimised for interactive use, behave just like Python objects
 - ⇒ user calls methods of the tools:

```
<toolname>.<methodname>( <parameters> )
```

- e.g., ms.open('mydata.ms') open an MS read-only with the MS tool
- anything possible with tasks is also possible using tools alone
- tasks are Python scripts using the tools + xml interface definition



```
import os
from taskinit import *
def flagautocorr(vis=None):
        casalog.origin('flagautocorr')
        try:
                fq.clearflagselection(0)
                if ((type(vis)==str) & (os.path.exists(vis))):
                         fq.open(vis)
                else:
                        raise Exception, 'Visibility data set not found'
                fq.setdata()
                fg.setmanualflags(autocorrelation=True)
                fq.run()
                fq.done()
                ms.open(vis, nomodify=False)
                ms.writehistory(message='flagautocorr',origin='flagautocorr')
                ms.close()
        except Exception, instance:
                fq.done()
                print '*** Error ***',instance
```



```
import os
from taskinit import * one input parameter
def flagautocorr(vis=None):
        casalog.origin('flagautocorr')
        try:
                fq.clearflagselection(0)
                if ((type(vis)==str) & (os.path.exists(vis))):
                        fq.open(vis)
                else:
                        raise Exception, 'Visibility data set not found'
                fq.setdata()
                fg.setmanualflags(autocorrelation=True)
                fq.run()
                fq.done()
                ms.open(vis, nomodify=False)
                ms.writehistory(message='flagautocorr',origin='flagautocorr')
                ms.close()
        except Exception, instance:
                fq.done()
                print '*** Error ***',instance
```



```
import os
  from taskinit import *
  def flagautocorr(vis=None):
           casalog.origin('flagautocorr')
           try:
autoflag tool \longrightarrow fg.clearflagselection(0)
                   if ((type(vis)==str) & (os.path.exists(vis))):
                       -->fq.open(vis)
                   else:
                           raise Exception, 'Visibility data set not found'
                 fq.setdata()
               fg.setmanualflags(autocorrelation=True)
               \rightarrow fg.run()
               fg.done()
                   ms.open(vis,nomodify=False)
                   ms.writehistory(message='flagautocorr',origin='flagautocorr')
                   ms.close()
           except Exception, instance:
               fg.done()
                   print '*** Error ***',instance
```



```
import os
   from taskinit import *
  def flagautocorr(vis=None):
          casalog.origin('flagautocorr')
          try:
              fg.clearflagselection(0)
                  if ((type(vis)==str) & (os.path.exists(vis))):
                      ->fq.open(vis)
                  else:
                          raise Exception, 'Visibility data set not found'
                fq.setdata()
                fg.setmanualflags(autocorrelation=True)
              fg.run()
              - fq.done()
               ms.open(vis,nomodify=False)
MS tool
                 ms.writehistory(message='flagautocorr',origin='flagautocorr')
                  ms.close()
          except Exception, instance:
              fg.done()
                  print '*** Error ***',instance
```



CASA global variables and task parameters

- casapy == Python shell with CASA extensions
- in casapy variables defined on the command line are global, i.e. scripts started with

```
execfile('scriptfilename')
have access to the variable values
```

```
Example:
    script "myscript.py":
        # test global variables
        print "value of a is ", a

command line:
        CASA <2>: a = 10
        CASA <3>: execfile('myscript.py')

output:
        value of a is 10
```



CASA global variables and task parameters

- taskname
 - = name of the current task which will be executed by go
- every task parameter name behaves like a global variable
 - \Rightarrow e.g., if you specify the input parameter field in a command line

```
field = 'NGC4826'
```

then field will keep this value until you change it, for all tasks!

- the parameters of all tasks are coherently named so they can be shared:

vis - the input MS

outputvis - the output MS

field - the selection condition on the field table in an MS

the selection condition on the spectral window table in an MS

...

- get help on a parameter by typing help par.<parametername>



casapy command line options

Useful casapy command line options:

Example: run a pipeline script non-interactively

casapy --nologger -c mypipeline.py



CASA Measurement Sets, ASDMs, and uvfits

- Internal CASA visibility data format is the Measurement Set (MS)

- Presently supported input formats:

ALMA: ALMA Science Data Model (ASDM)

EVLA: Science Data Model (SDM, same as the ASDM)

VLA: VLA archive format

FITS IDI: planned for later this year

and the transport format uvfits



CASA Measurement Sets, ASDMs, and uvfits

The MS

- relational database system with fixed structure made from CASA Tables
- consists of a main table with 15 required sub-tables + several optional ones
- uses OS directory structure (need to copy with cp R, remove with rm r)
- visibilities stored in the MAIN table
- no compression
- manipulate an MS with the ms and the tb tool or with browsetable()
- during processing, CASA may add "scratch columns" to the MS main table



CASA Measurement Sets, ASDMs, and uvfits

The **ASDM**

- relational database system with fixed structure
- consists of set of up to 56 tables (also observatory setup information!)
- uses OS directory structure (need to copy with cp R, remove with rm r)
- visibilities stored in the MAIN table
- no compression
- on disk, table descriptions in XML files, table data in binary MIME format files
- import into CASA using the task *importasdm* (for v1) or *importoldasdm* (for v0.9)
- in release 3.0.1 there is a beta-version of exportasdm (MS to ASDM)



CASA calibration tables

Calibration tables for visibility data

- CASA tables with defined columns and subtables
- contain calibration solutions and/or parametrisations
- serve communication between calibration tasks and storage of final result



CASA images and fits

Two formats for images in CASA:

- a) CASA images
 - based on CASA Tables
 - proper name in casacore: PagedImage
 - approach: make the image accessible as a multi-dimensional lattice
 - arbitrary size on disk, paged into memory

b) FITS

- translation to/from CASA images by importfits and exportfits tasks
- follows the IAU FITS standard v3.0 (2008)
- special additions for compatibility with AIPS for spectral image cube axes



History

- All CASA data formats contain history or log sub-tables

- Access via browsetable() or special tasks/tool methods:

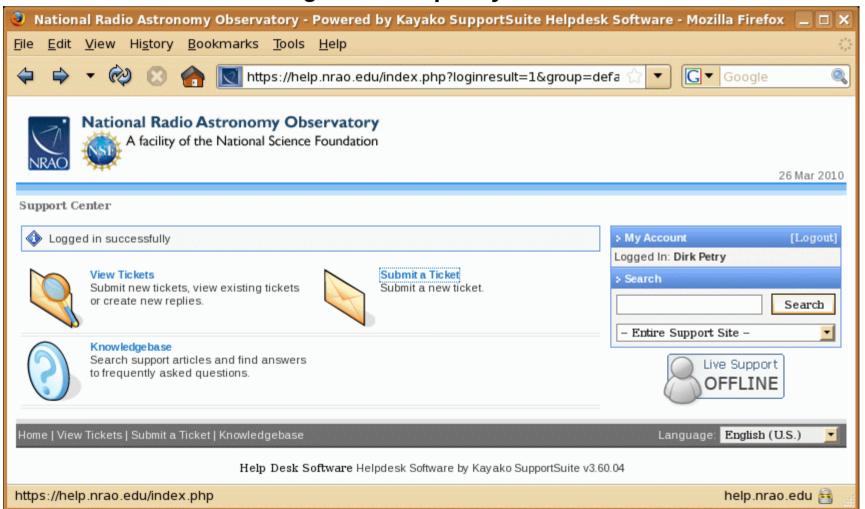
MS: listhistory() or ms.listhistory()

Image: ia.history()



What to do if you encounter a problem with *CASA*:

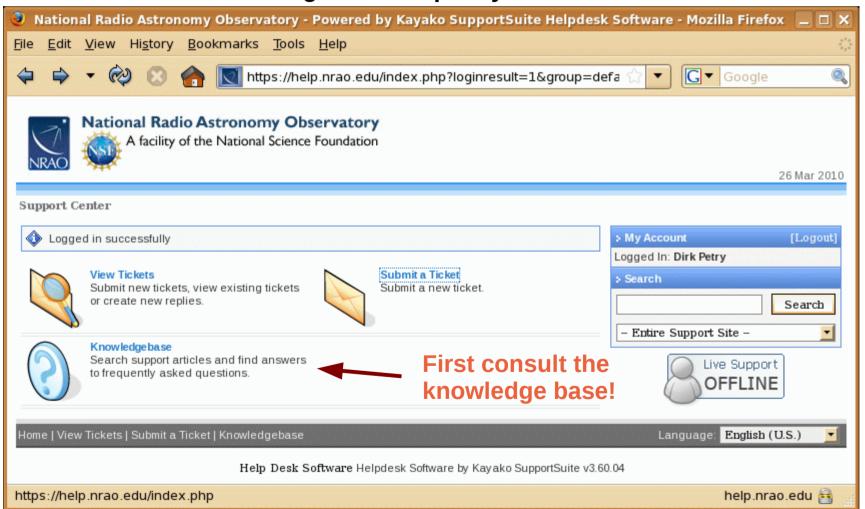
If the cookbook and the release notes don't help, go to http://help.nrao.edu/
Don't have an account? Register at http://my.nrao.edu





What to do if you encounter a problem with *CASA*:

If the cookbook and the release notes don't help, go to http://help.nrao.edu/
Don't have an account? Register at http://my.nrao.edu



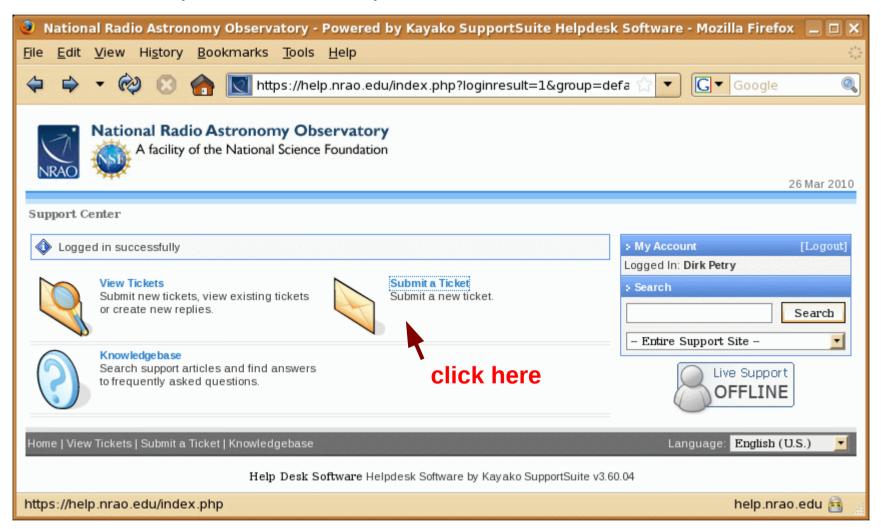


What to do if you encounter a problem with CASA and you can't find the solution in the documentation or the knowledge base:

- A) You think you might have found a bug in CASA
 - Try to reproduce your problem, ideally by writing a Python *script* which will demonstrate the problem.
 - Put your *test data (if needed)* on some web or ftp server where it can remain for at least several months.
 - File a helpdesk ticket including the script, a short description of the problem, and the URL of the data.
 - Need to mention CASA version and your operating system (32 bit or 64 bit?)
- B) You don't know how to perform a certain analysis task in CASA
 - If you can't make progress, then, as in (A) try to prepare a *script* for your analysis up to the point where you don't know how to go further.
 - File a helpdesk ticket including the script and a description of what you would like to achieve.

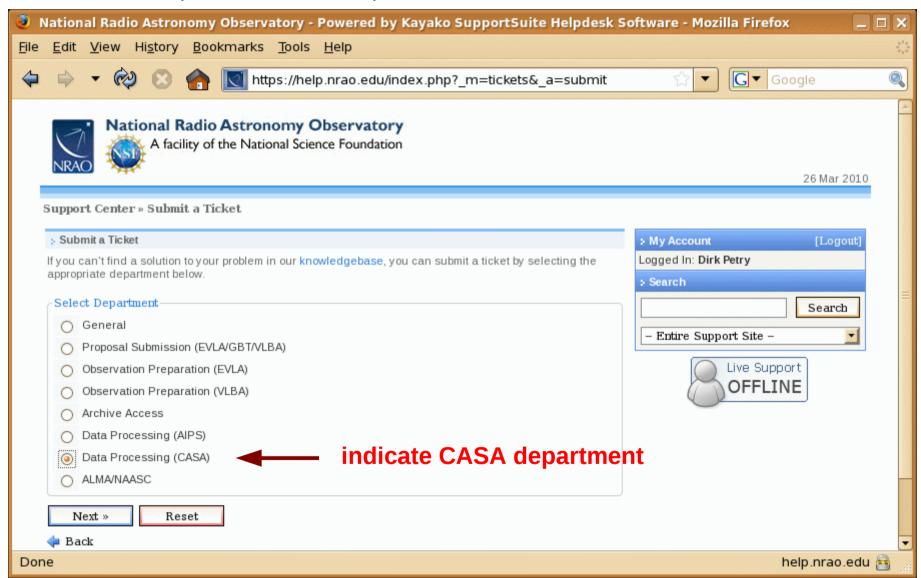


How to file a helpdesk ticket at help.nrao.edu:





How to file a helpdesk ticket at help.nrao.edu:





How to file a helpdesk ticket:

Where does your data come from? (identify necessary expertise)

Where do you come from? (who is responsible?)

What OS and CASA version are you using? (for reproducing your problem)

Give at least a description of what you are trying to do and the URL of your test data if needed to reproduce your problem.

Also quote error messages.

Upload a Python script which demonstrates your problem



D. Petry, Bologna CASA Workshop, April 20



